# Parameter Estimation for Stochastic Parabolic Equations: Asymptotic Properties of a Two-Dimensional Projection Based Estimate 

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#### Abstract

A two-dimensional parameter is estimated from the observations of a random field defined on a compact manifold by a stochastic parabolic equation. Unlike the previous works on the subject, the equation is not necessarily diagonalizable, and no assumptions are made about the eigenfunctions of the operators in the equation. The estimate is based on certain finite dimensional projections of the observed random field, and the asymptotic properties of the estimate are studied as the dimension of the projection is increased while the observation time is fixed. Simple conditions are found for the consistency and asymptotic normality of the estimate. An application to a problem in oceanography is discussed.


## 1 Introduction

Parameter estimation is an example of the inverse problem when the solution of some equation is observed and conclusions must be made about the coefficients of the equation. In the parametric setting the coefficients are assumed to depend on one or more scalar parameters. The estimate of the parameters should include only the information available to the observer, and should be consistent, i.e. approach the true value of the parameters as more and more information becomes available. Typically, the longer the observation time $T$ or the smaller the amplitude $\varepsilon$ of the random perturbation in the observations, the better the estimate. The asymptotic properties of the estimate are then studied in the limit $T \rightarrow \infty$ or $\varepsilon \rightarrow 0$.

When the observation process is finite dimensional, the only way to get a consistent estimate is to increase $T$ or to decrease $\varepsilon$. In some models, though, the observation process is a random field, i.e. a random function $u=u(t, x)$ depending on the time

[^0]variable $t$ and a $d$-dimensional space variable $x$. A typical example is the heat balance equation [1] describing the evolution of the sea surface temperature anomalies:
$$
d u(t, x)=\left(D \nabla^{2} u(t, x)-(\vec{v}(x), \nabla) u(t, x)-\lambda u(t, x)\right) d t+d W(t, x)
$$
with some initial and boundary conditions. Here $x$ belongs to a domain of $\mathbb{R}^{2}, \vec{v}$ is the velocity field of the top layer of the ocean, $W$ is the random perturbation representing the short-term atmospheric effects, $D$ and $\lambda$ are the parameters subject to estimation from the observations of $u$.

If the observation process is infinite dimensional, then it is possible to construct an estimate using a finite dimensional projection of the observations. Under certain conditions this projection-based estimate turns out to be consistent and asymptotically normal as the dimension $K$ of the projection increases while the observation time and the amplitude of noise remain fixed. The first example of this kind was studied in [4]. The observed random field in that example is diagonalizable, which means that there exists an orthonormal basis in a suitable Hilbert space so that the projections of the field on the elements of the basis are independent random processes. In subsequent works $[2,3,6,15]$ the general theory for diagonalizable random fields was developed. The partial differential equation describing such fields must have the following property: there exists an orthonormal basis in a suitable Hilbert space so that every element of the basis is an eigenfunction of every operator in the equation. The projection-based estimate in this case is the maximum likelihood estimate determined only by the first $K$ spatial Fourier coefficients of the observations.

To study the non-diagonalizable fields, one approach is to assume that, instead of the solution of the corresponding partial differential equation, the Galerkin approximation of the solution is observed [5, 3]. Another approach is to assume that the whole solution $u=u(t, x)$ is observed, but only finite dimensional projections are used to construct the estimate. Even though the resulting estimate is not the maximum likelihood, it still can be consistent and asymptotically normal under very natural assumptions. The possibility to measure $u$ at all points in space is essential: if an operator $\mathcal{A}$ in the equation does not commute with the corresponding projection operator $\Pi^{K}$, then, to evaluate $\Pi^{K} \mathcal{A} u$, it is not enough to know only $\Pi^{K} u$. Estimation of one parameter in this setting was studied in [13, 12]. The objective of the current work is to extend the results to the case of two unknown parameters. By considering only two parameters, it possible to analyze the effects related to multi-parameter estimation while stating all the assumptions in more explicit terms without using the general identifiability conditions.

A few words about terminology and notations. An estimate $\hat{\theta}^{K}$ of $\theta$ is called consistent if $\mathbf{P}-\lim _{K \rightarrow \infty}\left|\hat{\theta}^{K}-\theta\right|=0$, where $\mathbf{P}$-lim means convergence in probability. If $\theta$ is a scalar, the estimate is called asymptotically normal with rate $\Psi_{\theta}(K)$ if there exists an increasing to infinity sequence of real numbers $\Psi_{\theta}(K)$ such that the normalized estimation error $\Psi_{\theta}(K)\left(\hat{\theta}^{K}-\theta\right)$ converges in distribution to a Gaussian random vector. A Gaussian random variable with zero mean and unit variance will be denoted by $\mathcal{N}(0,1)$. For two sequences of non-negative numbers $a_{n}, b_{n}$, notation $a_{n} \asymp b_{n}$ means that the ratio $a_{n} / b_{n}$ is bounded from below and from above for all
sufficiently large $n$. Symbol * denotes the transpose of a vector or the adjoint of an operator.

## 2 The setting

Let $M$ be a $d$-dimensional compact orientable $\mathbf{C}^{\infty}$ manifold with a smooth positive measure $d x$. If $\mathcal{L}$ is an elliptic positive definite self-adjoint differential operator of order $2 m$ on $M$, then the operator $\Lambda=(\mathcal{L})^{1 /(2 m)}$ is elliptic of order 1 and generates the scale $\left\{\mathbb{H}^{s}\right\}_{s \in \mathbb{R}}$ of Sobolev spaces on $M[9,17]$. For simplicity, only real elements of $\mathbb{H}^{s}$ will be considered. When there is no danger of confusion, the variable $x$ will be omitted in the argument of functions defined on $M$.

In what follows, an alternative characterization of the spaces $\left\{\mathbb{H}^{s}\right\}$ will be used. By Theorem I.8.3 in [17], the operator $\mathcal{L}$ has a complete orthonormal system of eigenfunctions $\left\{e_{k}\right\}_{k \geq 1}$ in the space $L_{2}(M, d x)$ of square integrable functions on $M$. With no loss of generality it can be assumed that each $e_{k}(x)$ is real. Then for every $f \in L_{2}(M, d x)$ the representation

$$
f=\sum_{k \geq 1} \psi_{k}(f) e_{k}
$$

holds, where

$$
\psi_{k}(f)=\int_{M} f(x) e_{k}(x) d x
$$

If $l_{k}>0$ is the eigenvalue of $\mathcal{L}$ corresponding to $e_{k}$ and $\lambda_{k}:=l_{k}^{1 /(2 m)}$, then, for $s \geq 0$, $\mathbb{H}^{s}=\left\{f \in L_{2}(M, d x): \sum_{k \geq 1} \lambda_{k}^{2 s}\left|\psi_{k}(f)\right|^{2}<\infty\right\}$ and for $s<0, H^{s}$ is the closure of $L_{2}(M, d x)$ in the norm $\|f\|_{s}=\sqrt{\sum_{k \geq 1} \lambda_{k}^{2 s}\left|\psi_{k}(f)\right|^{2}}$. As a result, every element $f$ of the space $\mathbb{H}^{s}, s \in \mathbb{R}$, can be identified with a sequence $\left\{\psi_{k}(f)\right\}_{k \geq 1}$ such that $\sum_{k \geq 1} \lambda_{k}^{2 s}\left|\psi_{k}(f)\right|^{2}<\infty$. The space $\mathbb{H}^{s}$, equipped with the inner product

$$
\begin{equation*}
(f, g)_{s}=\sum_{k \geq 1} \lambda_{k}^{2 s} \psi_{k}(f) \psi_{k}(g), f, g \in \mathbb{H}^{s} \tag{2.1}
\end{equation*}
$$

is a Hilbert space.
A cylindrical Brownian motion $W=(W(t))_{0 \leq t \leq T}$ on $M$ is defined as follows: for every $t \in[0, T], W(t)$ is the element of $\cup_{s} \mathbb{H}^{s}$ such that $\psi_{k}(W(t))=w_{k}(t)$, where $\left\{w_{k}\right\}_{k \geq 1}$ is a collection of independent one dimensional Wiener processes on the given probability space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbf{P})$ with a complete filtration $\mathbb{F}=\left\{\mathcal{F}_{t}\right\}_{0 \leq t \leq T}$. Since by Theorem II.15.2 in [17] $\lambda_{k} \asymp k^{1 / d}, k \rightarrow \infty$, it follows that $W(t) \in H^{s}$ for every $s<-d / 2$. Direct computations show that $W$ is an $\mathbb{H}^{s}$ - valued Wiener process with the covariance operator $\Lambda^{2 s}$. This definition of $W$ agrees with the alternative definitions of the cylindrical Brownian motion [14, 18].

Let $\mathcal{A}, \mathcal{B}$, and $\mathcal{M}$ be differential or pseudo-differential operators on $M$ with smooth symbols that are not identically zero. Suppose that the orders $\operatorname{order}(\mathcal{A}), \operatorname{order}(\mathcal{B})$, and $\operatorname{order}(\mathcal{M})$ of the operators are such that $\max (\operatorname{order}(\mathcal{A}), \operatorname{order}(\mathcal{B}), \operatorname{order}(\mathcal{M}))<$ $2 m$.

Consider random field $u=u(t, x, \omega)$ defined for $t \in[0, T], x \in M, \omega \in \Omega$ by the evolution equation

$$
\begin{equation*}
d u(t)+\left[\theta_{1}(\mathcal{L}+\mathcal{A})+\theta_{2} \mathcal{B}+\mathcal{M}\right] u(t) d t=d W(t), 0<t \leq T, u(0)=0 \tag{2.2}
\end{equation*}
$$

In (2.2), $\theta_{1}>0, \theta_{2} \in \mathbb{R}$, and the dependence of $u$ and $W$ on $x$ and $\omega$ is suppressed. Assume that the values of $u(t, x)$ can be measured at all time moments $t \in[0, T]$ and all points $x \in M$. The problem is to estimate the parameters $\theta_{1}, \theta_{2}$ using these measurements.
2.1. Remark. The following model

$$
d u(t)+\left[\theta_{1} \mathcal{A}_{1}+\theta_{2} \mathcal{A}_{2}+\mathcal{M}\right] u(t) d t=\mathcal{R} d W(t), 0<t \leq T, u(0)=0
$$

is reduced to (2.2) if the operator $\mathcal{R}$ is invertible, $\theta_{1} \mathcal{A}_{1}+\theta_{2} \mathcal{A}_{2}$ is elliptic of order $2 m$ and bounded from below for all admissible values of parameters $\theta_{1}, \theta_{2}$, and $\operatorname{order}\left(\mathcal{A}_{1}\right) \neq$ $\operatorname{order}\left(\mathcal{A}_{2}\right)$. Indeed, set

$$
\tilde{u}(t, x)=\mathcal{R}^{-1} u(t, x), \quad \tilde{\mathcal{A}}_{1}=\mathcal{R}^{-1} \mathcal{A}_{1} \mathcal{R}, \quad \tilde{\mathcal{A}}_{2}=\mathcal{R}^{-1} \mathcal{A}_{2} \mathcal{R}, \quad \tilde{\mathcal{M}}=\mathcal{R}^{-1} \mathcal{M} \mathcal{R}
$$

If, for example, $\operatorname{order}\left(\mathcal{A}_{1}\right)=2 m$, then $\mathcal{L}=\left(\tilde{\mathcal{A}}_{1}+\tilde{\mathcal{A}}_{1}{ }^{*}\right) / 2+(c+1) I, \mathcal{A}=\left(\tilde{\mathcal{A}}_{1}-\right.$ $\left.\tilde{\mathcal{A}}_{1}{ }^{*}\right) / 2-(c+1) I, \mathcal{B}=\tilde{\mathcal{A}}_{2}$, where $c$ is the lower bound on eigenvalues of $\left(\tilde{\mathcal{A}}_{1}+\tilde{\mathcal{A}}_{1}{ }^{*}\right) / 2$ and $I$ is the identity operator. Indeed, by Corollary 2.1.1 in [9], if an operator $\mathcal{P}$ is of even order with real coefficients, then the operator $\mathcal{P}-\mathcal{P}^{*}$ is of lower order than $\mathcal{P}$.

Before the questions of parameter estimation can be addressed, it is necessary to determine the analytic properties of the field $u$. It can be shown that equation (2.2) fits the general framework of coercive stochastic evolution equations studied in [16].
2.2. Lemma. If $\mathcal{P}$ is a differential operator of order $p$ on $M$, then for every $s \in \mathbb{R}$ there exist positive constants $C_{1}$ and $C_{2}$, possibly depending on $s$, so that the inequality

$$
\begin{equation*}
((\mathcal{L}+\mathcal{P}) f, f)_{s} \geq C_{1}\|f\|_{s+m}^{2}-C_{2}\|f\|_{s}^{2} \tag{2.3}
\end{equation*}
$$

holds for every $f \in \mathbf{C}^{\infty}(M)$.
Proof. Clearly, $((\mathcal{L}+\mathcal{P}) f, f)_{s}=(\mathcal{L} f, f)_{s}+(\mathcal{P} f, f)_{s}$. By the definition of the norm $\|\cdot\|_{s}$,

$$
\|f\|_{s}^{2}=\left(\Lambda^{s} f, \Lambda^{s} f\right)_{0}
$$

Since $\mathcal{L}=\Lambda^{2 m}$,

$$
(\mathcal{L} f, f)_{s}=\|f\|_{s+m}
$$

Next,

$$
\left|(\mathcal{P} f, f)_{s}\right|=\left|\left(\Lambda^{s-m} \mathcal{P} f, \Lambda^{s+m} f\right)_{0}\right| \leq\|f\|_{s+m}\|f\|_{s-m+p}
$$

If $p \leq m$, then $\|f\|_{s-m+p} \leq C\|f\|_{s}$ so that

$$
\left|(\mathcal{P} f, f)_{s}\right| \leq C\|f\|_{s+m}\|f\|_{s} \leq C \epsilon\|f\|_{s+m}^{2}+C \epsilon^{-1}\|f\|_{s}^{2}, \epsilon>0
$$

and (2.3) follows if $\epsilon$ is sufficiently small.

If $m<p<2 m$, then use the property of the Hilbert scale [8, Definition III.1.1], according to which

$$
\|f\|_{s-p+m} \leq\|f\|_{s+m}^{\frac{p-m}{m}}\|f\|_{s}^{\frac{2 m-p}{m}}
$$

and also the following inequality

$$
|x y| \leq \epsilon \frac{|x|^{q}}{q}+\epsilon^{-q^{\prime} / q} \frac{|y|^{q^{\prime}}}{q^{\prime}}
$$

which is valid for every $\epsilon>0$ and $q, q^{\prime}>1,1 / q+1 / q^{\prime}=1$. Taking $1 / q=p /(2 m)$, $1 / q^{\prime}=1-p /(2 m)$ results in

$$
\left|(\mathcal{P} f, f)_{s}\right| \leq\|f\|_{s+m}^{2 / q}\|f\|_{m}^{2 / q^{\prime}} \leq \epsilon \frac{\|f\|_{s+m}^{2}}{q}+\epsilon^{-q / q^{\prime}} \frac{\|f\|_{s}^{2}}{q^{\prime}}
$$

and (2.3) follows if $\epsilon$ is sufficiently small.
2.3. Remark. Inequality (2.3) is one of many forms of the Gårding inequality.
2.4. Theorem. For every $s<-d / 2$ equation (2.2) has a unique solution $u=u(t)$ so that

$$
\begin{equation*}
u \in L_{2}\left(\Omega \times[0, T] ; \mathbb{H}^{s+m}\right) \cap L_{2}\left(\Omega ; \mathbf{C}\left([0, T] ; \mathbb{H}^{s}\right)\right) \tag{2.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbf{E} \sup _{t \in[0, T]}\|u(t)\|_{s}^{2}+\mathbf{E} \int_{0}^{T}\|u(t)\|_{s+m}^{2} d t \leq C T \sum_{k \geq 1} \lambda_{k}^{2 s}<\infty \tag{2.5}
\end{equation*}
$$

Proof. By assumption, $\max (\operatorname{order}(\mathcal{A}), \operatorname{order}(\mathcal{B}), \operatorname{order}(\mathcal{M}))<2 m$ and $\theta_{1}>0$. Then Lemma 2.2 implies that for every $s \in \mathbb{R}$ there exist positive constants $C_{1}$ and $C_{2}$ so that for every $f \in \mathbf{C}^{\infty}$

$$
-\left(\left(\theta_{1}(\mathcal{L}+\mathcal{A})+\theta_{2} \mathcal{B}+\mathcal{M}\right) f, f\right)_{s} \leq-C_{1}\|f\|_{s+m}^{2}+C_{2}\|f\|_{s}^{2}
$$

which means that the operator $-\left(\theta_{1}(\mathcal{L}+\mathcal{A})+\theta_{2} \mathcal{B}+\mathcal{M}\right)$ is coercive in every normal triple $\left\{\mathbb{H}^{s+m}, \mathbb{H}^{s}, \mathbb{H}^{s-m}\right\}$. The statement of the theorem now follows from the general result about the solvability of stochastic evolution equations in Hilbert spaces [16, Theorem 3.1.4].
2.5. Lemma. If $\mathcal{P}$ is a non-zero differential operator of order $p$ on $M$, then

$$
\begin{equation*}
\mathbf{P}\{\omega: \mathcal{P} u(t)=0 \text { for all } t \in[0, T]\}=0 . \tag{2.6}
\end{equation*}
$$

Proof. On the set $\{\omega: \mathcal{P} u(t)=0$ for all $t \in[0, T]\}$,

$$
\begin{equation*}
\int_{0}^{t} \mathcal{P}\left[\theta_{1}(\mathcal{L}+\mathcal{A})+\theta_{2} \mathcal{B}+\mathcal{M}\right] u(s) d s=\mathcal{P} W(t), \quad 0 \leq t \leq T \tag{2.7}
\end{equation*}
$$

and consequently, if $r+p+2 m<-d / 2$ and $0 \neq f \in \mathbb{H}^{r}$, then

$$
\int_{0}^{t}\left(\mathcal{P}\left[\theta_{1}(\mathcal{L}+\mathcal{A})+\theta_{2} \mathcal{B}+\mathcal{M}\right] u(s), f\right)_{r} d s=\left(W(t), \mathcal{P}^{*} f\right)_{r}
$$

According to (2.4) the left hand side of the last equality is a real valued process having, as a function of $t$, $\mathbf{P}$ - a.s. bounded variation. On the other hand,

$$
U(t)=\frac{\left(W(t), \mathcal{P}^{*} f\right)_{r}}{\left\|\Lambda^{r} \mathcal{P}^{*} f\right\|_{r}}
$$

is a standard one-dimensional Winer process and therefore, as a function of $t$, has unbounded variation with probability 1 . This means that equality (2.7) is possible only on a set of $\mathbf{P}$ - measure 0 .

## 3 The Estimate and Its Properties

For $f \in \cup_{s} \mathbb{H}^{s}$ and a positive integer $K$ define

$$
\Pi^{K} f=\sum_{n=1}^{K} \psi_{n}(f) e_{n}
$$

It follows from (2.2) that $\Pi^{K} u(t)$ satisfies

$$
d \Pi^{K} u(t)+\Pi^{K}\left(\theta_{1}(\mathcal{L}+\mathcal{A})+\theta_{2} \mathcal{B}+\mathcal{M}\right) u(t) d t=d W^{K}(t)
$$

where $W^{K}(t)=\Pi^{K} W(t)$. Assume for a moment that the operators $\mathcal{A}, \mathcal{B}$, and $\mathcal{M}$ commute with $\Pi^{K}$ for all $K$. Then the processes $\Pi^{K} u$ can be viewed as a diffusion process and the maximum likelihood estimate of $\theta_{1}, \theta_{2}$ can be obtained [2] using the results from [11] about the absolute continuity of measures generated by diffusion processes.

To write down the estimate, introduce the following notations:

$$
\begin{gathered}
J_{1}(K)=\int_{0}^{T}\left\|\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t)\right\|_{0}^{2} d t, \quad J_{2}(K)=\int_{0}^{T}\left\|\Pi^{K} \mathcal{B} u(t)\right\|_{0}^{2} d t \\
J_{12}(K)=\int_{0}^{T}\left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), \Pi^{K} \mathcal{B} u(t)\right)_{0} d t
\end{gathered}
$$

Then estimates $\hat{\theta}_{1}^{K}, \hat{\theta}_{2}^{K}$ of $\theta_{1}, \theta_{2}$ are defined as the solution of

$$
\left(\begin{array}{cc}
J_{1}(K) & J_{12}(K)  \tag{3.1}\\
J_{12}(K) & J_{2}(K)
\end{array}\right)\binom{\hat{\theta}_{1}^{K}}{\hat{\theta}_{2}^{K}}=\left(\begin{array}{cc}
-\int_{0}^{T} & \left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), d \Pi^{K} u(t)+\Pi^{k} \mathcal{M} u(t) d t\right)_{0} \\
& -\int_{0}^{T}\left(\Pi^{K} \mathcal{B} u(t), d \Pi^{K} u(t)+\Pi^{k} \mathcal{M} u(t) d t\right)_{0}
\end{array}\right) .
$$

It follows from Lemma 2.5 and the Cauchy-Schwartz inequality that

$$
\mathbf{P}\left(\left|J_{12}(K)\right|^{2}<J_{1}(K) J_{2}(K)\right)=1
$$

for all sufficiently large $K$, and consequently the estimates are well defined at least for sufficiently large $K$ :

$$
\begin{align*}
\hat{\theta}_{1}^{K}=( & \left.J_{1}(K) J_{2}(K)-\left|J_{12}(K)\right|^{2}\right)^{-1}\left(J_{12}(K) \int_{0}^{T}\left(\Pi^{K} \mathcal{B} u(t), d \Pi^{K} u(t)+\Pi^{k} \mathcal{M} u(t) d t\right)_{0}\right. \\
& \left.-J_{2}(K) \int_{0}^{T}\left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), d \Pi^{K} u(t)+\Pi^{k} \mathcal{M} u(t) d t\right)_{0}\right) \\
\hat{\theta}_{2}^{K}= & \left(J_{1}(K) J_{2}(K)-\left|J_{12}(K)\right|^{2}\right)^{-1}\left(-J_{1}(K) \int_{0}^{T}\left(\Pi^{K} \mathcal{B} u(t), d \Pi^{K} u(t)+\Pi^{k} \mathcal{M} u(t) d t\right)_{0}\right. \\
& \left.+J_{12}(K) \int_{0}^{T}\left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), d \Pi^{K} u(t)+\Pi^{k} \mathcal{M} u(t) d t\right)_{0}\right) \tag{3.2}
\end{align*}
$$

In general the process $\Pi^{K} u=\left(\Pi^{K} u(t), \mathcal{F}_{t}\right)_{0 \leq t \leq T}$ is determined by the whole trajectory of $u$ and is just an Ito process so that the maximum likelihood estimate of the parameters is not easily computable. On the other hand, all expressions on the right hand side of (3.2) can be computed as long as the trajectory $u$ is known, and therefore $\hat{\theta}_{1}^{K}, \hat{\theta}_{2}^{K}$ can still be tried as estimates of $\theta_{1}, \theta_{2}$. The vector $\left(\hat{\theta}_{1}^{K}, \hat{\theta}_{2}^{K}\right)^{*}$ with $\hat{\theta}_{1}^{K}, \hat{\theta}_{2}^{K}$ given by (3.2) will be referred to as the projection-based estimate of the vector parameter $\left(\theta_{1}, \theta_{2}\right)^{*}$. The asymptotic properties, as $K \rightarrow \infty$, of this estimate are studied below.

Using the following notations

$$
\begin{gathered}
D(K):=\frac{\left|J_{12}(K)\right|^{2}}{J_{1}(K) J_{2}(K)}, \quad \zeta_{1}(K)=\int_{0}^{T}\left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), d W^{K}(t)\right)_{0} \\
\zeta_{2}(K)=\int_{0}^{T}\left(\Pi^{K} \mathcal{B} u(t), d W^{K}(t)\right)_{0}
\end{gathered}
$$

it is possible to rewrite (3.2) as

$$
\begin{align*}
& \hat{\theta}_{1}^{K}=\theta_{1}+\frac{\zeta_{1}(K) / J_{1}(K)-\left(J_{12}(K) / J_{1}(K)\right)\left(\zeta_{2}(K) / J_{2}(K)\right)}{1-D(K)} \\
& \hat{\theta}_{2}^{K}=\theta_{2}+\frac{\zeta_{2}(K) / J_{2}(K)-\left(J_{12}(K) / J_{2}(K)\right)\left(\zeta_{1}(K) / J_{1}(K)\right)}{1-D(K)} \tag{3.3}
\end{align*}
$$

Although not suitable for computations, representation (3.3) is convenient for studying the asymptotic properties of the estimate.

It is natural to expect that the estimate $\hat{\theta}_{1}^{K}$ is consistent since the information about $\theta_{1}$ is contained in the term $(\mathcal{L}+\mathcal{A}) u$, and this term is more irregular than the noise $W$. The irregularity of a particular term in the equation can be ensured if the corresponding operator has sufficiently high order and "maintains" that order on a wide class of functions. The following definition gives the precise meaning to the last requirement.
3.1. Definition. A differential operator $\mathcal{P}$ of order $p$ on $M$ is called essentially non-degenerate if for every $s \in \mathbb{R}$ there exist positive numbers $\varepsilon, L, \delta$ so that the inequality

$$
\begin{equation*}
\|\mathcal{P} f\|_{s}^{2} \geq \varepsilon\|f\|_{s+p}^{2}-L\|f\|_{s+p-\delta}^{2} \tag{3.4}
\end{equation*}
$$

holds for all $f \in \mathbf{C}^{\infty}(M)$.
3.2. Remark. If the operator $\mathcal{P}^{*} \mathcal{P}$ is elliptic of order $2 p$, then, by Lemma 2.2 , the operator $\mathcal{P}$ is essentially non-degenerate because in this case the operator $\mathcal{P}^{*} \mathcal{P}$ is positive definite and self-adjoint so that the operator $\left(\mathcal{P}^{*} \mathcal{P}\right)^{1 /(2 p)}$ generates an equivalent scale of Sobolev spaces on $M$. In particular, every elliptic operator satisfies (3.4). Since, by Corollary 2.1.2 in [9], for every differential operator $\mathcal{P}$ the operator $\mathcal{P}^{*} \mathcal{P}-\mathcal{P} \mathcal{P}^{*}$ is of order $2 p-1$, the operator $\mathcal{P}$ is essentially non-degenerate if and only if $\mathcal{P}^{*}$ is.
3.3. Remark. If $\mathcal{P}=\mathcal{L}+\mathcal{A}$, then non-degeneracy condition (3.4) holds with $p=2 m, \varepsilon=1, \delta=m-\operatorname{order}(\mathcal{A}) / 2$, because

$$
\|\mathcal{L} f\|_{s}=\|f\|_{s+2 m}
$$

and, since the order of the operator $\mathcal{A}^{*} \mathcal{L}$ is $4 m-2 \delta$,

$$
\begin{aligned}
& \left(\mathcal{A}^{*} \mathcal{L} f, f\right)_{s}=\left(\Lambda^{-(2 m-\delta)} \mathcal{A}^{*} \mathcal{L} f, \Lambda^{2 m-\delta} f\right)_{s} \leq \\
& \left\|\Lambda^{-(2 m-\delta)} \mathcal{A}^{*} \mathcal{L} f\right\|_{s}\left\|\Lambda^{2 m-\delta} f\right\|_{s} \leq C\|f\|_{s+2 m-\delta}^{2}
\end{aligned}
$$

In what follows, the order of the operator $\mathcal{B}$ is denoted by $b$. Also define

$$
\Psi_{1}(K)=\sqrt{\mathbf{E} J_{1}(K)}, \quad \Psi_{2}(K)=\sqrt{\mathbf{E} J_{2}(K)}
$$

The next lemma is a collection of technical results to be used later.

### 3.4. Lemma.

1. 

$$
\begin{gathered}
\mathbf{E} J_{1}(K) \asymp K^{2 m / d+1} ; \quad \mathbf{P}-\lim _{K \rightarrow \infty} \frac{J_{1}(K)}{\mathbf{E} J_{1}(K)}=1 ; \quad \mathbf{P}-\lim _{K \rightarrow \infty} \frac{\zeta_{1}(K)}{J_{1}(K)}=0 ; \\
\lim _{K \rightarrow \infty} \frac{\zeta_{1}(K)}{\Psi_{1}(K)}=\mathcal{N}(0,1) \text { in distribution. }
\end{gathered}
$$

2. If $b<m-d / 2$, then
$\lim _{K \rightarrow \infty} \mathbf{E} J_{2}(K)=\int_{0}^{T} \mathbf{E}\|\mathcal{B} u(t)\|_{0}^{2} d t<\infty, \quad \mathbf{P}-\lim _{K \rightarrow \infty} \zeta_{2}(K)=\int_{0}^{T}(\mathcal{B} u(t), d W(t))_{0}$.
3. If $b \geq m-d / 2$ and the operator $\mathcal{B}$ is essentially non-degenerate, then
4. $\mathbf{E} J_{2}(K) \asymp \sum_{n=1}^{K} n^{2(b-m) / d} ; \quad \mathbf{P}-\lim _{K \rightarrow \infty} \frac{J_{2}(K)}{\mathbf{E} J_{2}(K)}=1 ; \quad \mathbf{P}-\lim _{K \rightarrow \infty} \frac{\zeta_{2}(K)}{J_{2}(K)}=0 ;$
$\lim _{K \rightarrow \infty} \frac{\zeta_{2}(K)}{\Psi_{2}(K)}=\mathcal{N}(0,1)$ in distribution.

Proof. With Remark 3.3 in mind, the first and the third parts of the theorem follow from Lemma A. 1 and Corollary A. 4 in appendix. The second part is a consequence of (2.5).
3.5. Theorem. Assume that $b<m-d / 2$.

1. The estimate $\hat{\theta}_{1}^{K}$ of $\theta_{1}$ is consistent and asymptotically normal with the rate $\Psi_{1}(K) \asymp K^{m / d+1 / 2}:$

$$
\mathbf{P}-\lim _{K \rightarrow \infty}\left|\hat{\theta}_{1}^{K}-\theta_{1}\right|=0, \lim _{K \rightarrow \infty} \Psi_{1}(K)\left(\hat{\theta}_{1}^{K}-\theta_{1}\right)=\mathcal{N}(0,1) \text { in distribution. }
$$

2. The estimate $\hat{\theta}_{2}^{K}$ of $\theta_{2}$ is asymptotically biased:

$$
\mathbf{P}-\lim _{K \rightarrow \infty} \hat{\theta}_{2}^{K}=\theta_{2}+\frac{\int_{0}^{T}(\mathcal{B} u(t), d W(t))_{0}}{\int_{0}^{T}\|\mathcal{B} u(t)\|_{0}^{2} d t} .
$$

Proof. The first step is to show that $\mathbf{P}-\lim _{K \rightarrow \infty} D(K)=0$. To this end define

$$
A_{n}^{2}=\int_{0}^{T}\left|\psi_{n}((\mathcal{L}+\mathcal{A}) u(t))\right|^{2} d t, B_{n}^{2}=\int_{0}^{T}\left|\psi_{n}(\mathcal{B} u(t))\right|^{2} d t
$$

and also $a_{n}^{2}=\mathbf{E} A_{n}^{2}$. By Lemma 3.4,

$$
\sum_{n=1}^{K} a_{n}^{2} \asymp K^{2 m / d+1}, \quad \sum_{n \geq 1} B_{n}^{2}=\int_{0}^{T}\|\mathcal{B} u(t)\|_{0}^{2} d t<\infty
$$

and by Lemma 2.5, $\sum_{n=1}^{K} B_{n}^{2}>0 \mathbf{P}$ - a.s. for all sufficiently large $K$. It is also clear that

$$
J_{1}(K)=\sum_{n=1}^{K} A_{n}^{2}, \quad J_{2}(K)=\sum_{n=1}^{K} B_{n}^{2} .
$$

Fix some $0<\gamma<1$. By the Cauchy-Schwartz inequality,

$$
\begin{equation*}
\left|J_{12}\right| \leq\left(\sum_{n \leq \gamma K} A_{n}^{2}\right)^{1 / 2}\left(\sum_{n \leq \gamma K} B_{n}^{2}\right)^{1 / 2}+\left(\sum_{\gamma K<n \leq K} A_{n}^{2}\right)^{1 / 2}\left(\sum_{\gamma K<n \leq K} B_{n}^{2}\right)^{1 / 2} . \tag{3.5}
\end{equation*}
$$

By Lemma 3.4 P- $\lim _{K \rightarrow \infty} \sum_{n=1}^{K} A_{n} / \sum_{n=1}^{K} a_{n}^{2}=1$ so that

$$
\sqrt{D(K)} \leq C \gamma^{m / d+1 / 2} X_{\gamma}(K)+Y_{\gamma}(K)
$$

where $C>0$ is an absolute constant and the non-negative random variables $X_{\gamma}(K), Y_{\gamma}(K)$ are such that $\mathbf{P}-\lim _{K \rightarrow \infty} X_{\gamma}(K)=1, \mathbf{P}-\lim _{K \rightarrow \infty} Y_{\gamma}(K)=0$ for every $\gamma \in(0,1)$. Since $\gamma$ can be taken arbitrarily close to 0 , it follows that $\mathbf{P}-\lim _{K} D(K)=0$. To complete the proof of the theorem, it remains to use (3.3) and Lemma 3.4.
3.6. Theorem. Assume that $b \geq m-d / 2$ and the operator $\mathcal{B}$ is essentially nondegenerate. Then both estimates $\hat{\theta}_{1}^{\bar{K}}$ and $\hat{\theta}_{2}^{K}$ are consistent.

Proof. According to representation (3.3) and Lemma 3.4, it is sufficient to check that there exists $\delta \in(0,1)$ so that

$$
\lim _{K \rightarrow \infty} \mathbf{P}(D(K)>\delta)=0
$$

Define $A_{n}^{2}, a_{n}^{2}, B_{n}^{2}$ as in the proof of Theorem 3.5, and also introduce $b_{n}^{2}=\mathbf{E} B_{n}^{2}$. By Lemma 3.4

$$
\begin{equation*}
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\sum_{n=1}^{K} A_{n}^{2}}{\sum_{n=1}^{K} a_{n}^{2}}=1, \quad \mathbf{P}-\lim _{K \rightarrow \infty} \frac{\sum_{n=1}^{K} B_{n}^{2}}{\sum_{n=1}^{K} b_{n}^{2}}=1 \tag{3.6}
\end{equation*}
$$

If $b=m-d / 2$, then $\sum_{n=1}^{K} b_{n}^{2} \asymp \ln K$, and (3.5) implies

$$
\sqrt{D(K)} \leq C \gamma^{m / d+1 / 2} X_{\gamma}(K)+Y_{\gamma}(K)
$$

where $C>0$ is an absolute constant and the non-negative random variables $X_{\gamma}(K), Y_{\gamma}(K)$ are such that $\mathbf{P}-\lim _{K \rightarrow \infty} X_{\gamma}(K)=1, \mathbf{P}-\lim _{K \rightarrow \infty} Y_{\gamma}(K)=0$ for every $\gamma \in(0,1)$. Since $\gamma$ can be taken arbitrarily close to 0 , it follows that $\mathbf{P}-\lim _{K} D(K)=0$.

If $b>m-d / 2$, define $\alpha=2 m / d, \beta=2(b-m) / d<\alpha$. Then (3.5) and (3.6) imply that for sufficiently small $\gamma>0$

$$
\begin{aligned}
\sqrt{D(K)} & \leq C_{1} \gamma^{(\alpha+\beta) / 2+1}+\left(1-C_{2} \gamma^{\alpha+1}\right)^{1 / 2}\left(1-C_{2} \gamma^{\beta+1}\right)^{1 / 2} \\
& +I\left(\left|X_{\gamma}(K)-1\right|>1 / 2\right)+I\left(\left|Y_{\gamma}(K)-1\right|>1 / 2\right)
\end{aligned}
$$

for some numbers $C_{1}, C_{2}$ and random variables $X_{\gamma}(K), Y_{\gamma}(K)$ which, for each $\gamma$, converge in probability to 1 as $K \rightarrow \infty$. Since

$$
C_{1} \gamma^{(\alpha+\beta) / 2+1}+\left(1-C_{2} \gamma^{\alpha+1}\right)^{1 / 2}\left(1-C_{2} \gamma^{\beta+1}\right)^{1 / 2}=1-C \gamma^{\beta+1}+\phi(\gamma),
$$

where $\lim _{\gamma \rightarrow 0} \gamma^{-\beta-1} \phi(\gamma)=0$, it follows that for $\delta$ sufficiently close to 1 and $\gamma$ sufficiently close to 0 ,
$\lim _{K \rightarrow \infty} \mathbf{P}(\sqrt{D(K)}>\delta) \leq \lim _{K \rightarrow \infty}\left(\mathbf{P}\left(\left|X_{\gamma}(K)-1\right|>1 / 2\right)+\mathbf{P}\left(\left|Y_{\gamma}(K)-1\right|>1 / 2\right)\right)=0$, which completes the proof of the theorem.

Lemma 3.4 and representation (3.3) imply that $\Psi_{1}(K), \Psi_{2}(K)$ should be the normalizing factors to study the limiting distribution of the vector $\left(\hat{\theta}_{1}^{K}-\theta_{1}, \hat{\theta}_{2}^{K}-\theta_{2}\right)^{*}$. In general, though, it is hardly possible to conclude anything about this distribution without the convergence of $D(K)$ to a deterministic limit. Unless the limit of $D(K)$ is zero, convergence or even relative compactness of the sequence $\{D(K)\}_{K \geq 1}$ requires additional non-degeneracy of the operator $\mathcal{B}$.
3.7. Theorem. Assume that $b \geq m-d / 2$ and the operator $\mathcal{B}$ is essentially nondegenerate.

1. If $b=m-d / 2$, then $\mathbf{P}-\lim _{K \rightarrow \infty} D(K)=0$ and the sequence of vectors

$$
\begin{equation*}
\left\{\left(\Psi_{1}(K)\left(\hat{\theta}_{1}^{K}-\theta_{1}\right), \Psi_{2}(K)\left(\hat{\theta}_{2}^{K}-\theta_{2}\right)\right)^{*}\right\}_{K \geq 1} \tag{3.7}
\end{equation*}
$$

converges in distribution to a two-dimensional Gaussian random vector with zero mean and unit covariance matrix.
2. If $b>m-d / 2$ and the operator $\mathcal{B}$ is elliptic, then every subsequence of (3.7) contains a further subsequence which converges to a two-dimensional Gaussian random vector with zero mean and some non-singular covariance matrix.

Proof. 1. Convergence of $D(K)$ to zero was established during the proof of Theorem 3.6. After that it remains to use (3.3) and Lemma 3.4.
2. The key step is to show that $J_{12} / \mathbf{E} J_{12}$ converges in probability to one, which is done in appendix, Lemma A.5. Together with Lemma 3.4 this convergence implies that

$$
\sqrt{D(K)}=X(K) \frac{\mathbf{E} J_{12}(K)}{\Psi_{1}(K) \Psi_{2}(K)},
$$

where $\mathbf{P}-\lim _{K \rightarrow \infty} X(K)=1$. It remains to show that every subsequence of

$$
\left\{\mathbf{E} J_{12}(K) /\left(\Psi_{1}(K) \Psi_{2}(K)\right)\right\}_{K \geq 1}
$$

has a further subsequence which converges to some $\delta<1$. To this end define

$$
a_{n}^{2}=\int_{0}^{T} \mathbf{E}\left|\psi_{n}((\mathcal{L}+\mathcal{A}) u(t))\right|^{2} d t, b_{n}^{2}=\int_{0}^{T} \mathbf{E}\left|\psi_{n}(\mathcal{B} u(t))\right|^{2} d t
$$

Then for sufficiently small $\gamma>0$,

$$
\begin{gathered}
\limsup _{K} \frac{\mathbf{E} J_{12}(K)}{\Psi_{1}(K) \Psi_{2}(K)} \\
\leq C_{1} \gamma^{(\alpha+\beta) / 2+1}+\left(1-C_{2} \gamma^{\alpha+1}\right)^{1 / 2}\left(1-C_{2} \gamma^{\beta+1}\right)^{1 / 2} \leq 1-C \gamma^{\beta+1}+o\left(\gamma^{\beta+1}\right)<1 .
\end{gathered}
$$

As a result, every subsequence of $\{D(K)\}_{K \geq 1}$ has a further subsequence which converges in probability to a deterministic limit $\delta<1$. By Lemma 3.4 the corresponding limiting distribution of (3.7) is a two-dimensional Gaussian random vector with zero mean and the covariance matrix

$$
\left(\begin{array}{rrr}
\frac{1}{1-\delta^{2}} & & -\frac{\delta}{(1-\delta)(1+\delta)^{2}} \\
-\frac{1}{(1-\delta)(1+\delta)^{2}} & \frac{1}{1-\delta^{2}}
\end{array}\right)
$$

3.8. Remark. Analysis of the proofs shows that the assumption about essential non-degeneracy of the operator $\mathcal{B}$ can be replaced by

$$
\sum_{n=1}^{K}\left\|\mathcal{B} e_{n}\right\|_{-m}^{2} \asymp \sum_{n=1}^{K} n^{2(b-m) / d}
$$

and the assumption about the ellipticity of $\mathcal{B}$, by

$$
\left|\sum_{n=1}^{K}\left(\mathcal{B} e_{n}, e_{n}\right)_{0}\right| \asymp K^{b / d+1}
$$

## 4 An Example

Consider the following stochastic partial differential equation:

$$
\begin{equation*}
d u(t, x)=\left(D \nabla^{2} u(t, x)-(\vec{v}(x), \nabla) u(t, x)-\lambda u(t, x)\right) d t+d W(t, x) \tag{4.1}
\end{equation*}
$$

It is called the heat balance equation and describes the dynamics of the sea surface temperature anomalies [1]. In (4.1), $x=\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}, \vec{v}(x)=\left(v_{1}\left(x_{1}, x_{2}\right), v_{2}\left(x_{1}, x_{2}\right)\right)$ is the velocity field of the top layer of the ocean $(\vec{v}(x)$ is assumed to be known), $D>0$ is called thermodiffusivity, $\lambda \in \mathbb{R}$, the cooling coefficient. The equation is considered on a rectangle $\left|x_{1}\right| \leq a ;\left|x_{2}\right| \leq c$ with periodic boundary conditions $u\left(t,-a, x_{2}\right)=$ $u\left(t, a, x_{2}\right), u\left(t, x_{1},-c\right)=u\left(t, x_{1}, c\right)$ and zero initial condition. This reduces (4.1) to the general model (2.2) with $M$ being a torus, $d=2, \mathcal{L}=-\nabla^{2}=-\partial^{2} / \partial x_{1}^{2}-\partial^{2} / \partial x_{2}^{2}, \mathcal{A}=$ $0, \mathcal{B}=I$ (the identity operator), $\mathcal{M}=(\vec{v}, \nabla)=v_{1}\left(x_{1}, x_{2}\right) \partial / \partial x_{1}+v_{2}\left(x_{1}, x_{2}\right) \partial / \partial x_{2}$, $\theta_{1}=D, \theta_{2}=\lambda$. Then $2 m=\operatorname{order}(\mathcal{L})=2, \operatorname{order}(\mathcal{A})=0, b=\operatorname{order}(\mathcal{B})=0$, and $\operatorname{order}(\mathcal{M})=1$. The basis $\left\{e_{k}\right\}_{k \geq 1}$ is a suitably ordered collection of real and imaginary parts of

$$
g_{n_{1}, n_{2}}\left(x_{1}, x_{2}\right)=\frac{1}{\sqrt{4 a c}} \exp \left\{\sqrt{-1} \pi\left(x_{1} n_{1} / a+x_{2} n_{2} / c\right)\right\}, n_{1}, n_{2} \geq 0
$$

Since $b=0=m-d / 2$, Theorems 3.6 and 3.7 imply that the joint projection-based estimate of $D$ and $\lambda$ is consistent and asymptotically normal, the rates of convergence are $\Psi_{D}(K) \asymp K, \Psi_{\lambda}(K) \asymp \sqrt{\ln K}$, and the limiting distribution is standard Gaussian. The result still holds if the noise term $W$ has some spatial covariance operator as long as $\left\{e_{k}\right\}_{k \geq 1}$ are the eigenfunctions of that operator.

Unlike the diagonalizable case, the proposed approach allows a non-constant velocity field. Still, a significant limitation is that the value of $\vec{v}(x)$ must be known.

## 5 Conclusion

A projection - based estimate of two unknown parameters $\theta_{1}, \theta_{2}$ can be constructed if the random field $u=u(t, x)$, containing the information about the parameters and defined on a compact $d$-dimensional manifold $M$ by the equation
$d u(t, x)+\left(\theta_{1} \mathcal{A}_{1}+\theta_{2} \mathcal{A}_{2}+\mathcal{M}\right) u(t, x) d t=d W(t, x), 0<t \leq T, u(0, x)=0, T$ fixed,
can be observed at all points $x \in M, 0 \leq t \leq T$. As the dimension of the projections tends to infinity, the joint estimate is consistent if $\mathcal{A}_{1}$ is an elliptic bounded below operator of order $2 m, \mathcal{A}_{2}$ is an essentially non-degenerate operator of order $b$ with $m-d / 2 \leq b<2 m$, and $\operatorname{order}(\mathcal{M})<2 m$. If $\mathcal{A}_{2}$ is an elliptic operator, then the appropriately normalized estimation errors form a relatively compact (in distribution sense) sequence with all the limiting distributions Gaussian.

## 6 Acknowledgments

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## Appendix

The following general result [2] is essential for the proofs of both consistency and asymptotic normality.
A.1. Lemma. If $\mathcal{P}$ is a differential operator on $M$ and

$$
\begin{equation*}
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t}=1, \tag{A.1}
\end{equation*}
$$

then

$$
\begin{equation*}
\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left(\Pi^{K} \mathcal{P} u(t), d W^{K}(t)\right)_{0} d t}{\sqrt{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t}}=\mathcal{N}(0,1) \tag{A.2}
\end{equation*}
$$

in distribution.
Proof.
If

$$
M_{t}^{K}:=\frac{\int_{0}^{t}\left(\Pi^{K} \mathcal{P} u(s), d W^{K}(s)\right)_{0} d s}{\sqrt{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(s)\right\|_{0}^{2} d s}},
$$

then $\left(M_{t}^{K}, \mathcal{F}_{t}\right)_{0 \leq t \leq T}$ is a continuous square integrable martingale with quadratic characteristic

$$
\left\langle M^{K}\right\rangle_{t}=\frac{\int_{0}^{t}\left\|\Pi^{K} \mathcal{P} u(s)\right\|_{0}^{2} d s}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(s)\right\|_{0}^{2} d s}
$$

By assumption, $\mathbf{P}-\lim _{K \rightarrow \infty}\left\langle M^{K}\right\rangle_{T}=1$.
On the other hand, if $\left(w_{1}(t), \mathcal{F}_{t}\right)_{0 \leq t \leq T}$ is a one-dimensional Wiener process (e.g., $\left.w_{1}(t)=\psi_{1}(W(t))\right)$ and $M_{t}:=w_{1}(t) / \sqrt{T}$, then $\left(M_{t}, \mathcal{F}_{t}\right)_{0 \leq t \leq T}$ is a continuous square integrable martingale, $\langle M\rangle_{T}=1$.

As a result,

$$
\lim _{K \rightarrow \infty} M_{T}^{K}=M_{T}
$$

in distribution by [7, Theorem VIII.4.17] or [10, Theorem 5.5.4(II)]. Since $M_{T}$ is a Gaussian random variable with zero mean and unit variance, (A.2) follows.

Once (A.1) and (A.2) hold and

$$
\lim _{K \rightarrow \infty} \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t=+\infty
$$

the convergence

$$
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left(\Pi^{K} \mathcal{P} u(t), d W^{K}(t)\right)_{0} d t}{\int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t}=0
$$

follows. The objective, therefore, is to establish (A.1) and compute the asymptotics of $\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t$ for a suitable operator $\mathcal{P}$.

If $\psi_{k}(t):=\psi_{k}(u(t))$, then (2.2) implies

$$
d \psi_{k}(t)=-\theta_{1} l_{k} \psi_{k}(t)-\psi_{k}\left(\left(\theta_{1} \mathcal{A}+\theta_{2} \mathcal{B}+\mathcal{M}\right) u(t)\right) d t+d w_{k}(t), \psi_{k}(0)=0
$$

According to the variation of parameters formula, the solution of this equation is given by $\psi_{k}(t)=\xi_{k}(t)+\eta_{k}(t)$, where

$$
\begin{aligned}
& \xi_{k}(t)=\int_{0}^{t} e^{-\theta_{1} l_{k}(t-s)} d w_{k}(s) \\
& \eta_{k}(t)=-\int_{0}^{t} e^{-\theta_{1} l_{k}(t-s)} \psi_{k}\left(\left(\theta_{1} \mathcal{A}+\theta_{2} \mathcal{B}+\mathcal{M}\right) u(s)\right) d s
\end{aligned}
$$

If $\xi(t)$ and $\eta(t)$ are the elements of $\cup_{s} \mathbb{H}^{s}$ defined by the sequences $\left\{\xi_{k}(t)\right\}_{k \geq 1}$ and $\left\{\eta_{k}(t)\right\}_{k \geq 1}$ respectively, then the solution of (2.2) can be written as $u(t)=\xi(t)+\eta(t)$.

The following technical result will be used in the future.
A.2. Lemma. If $a>0$ and $f(t) \geq 0$, then

$$
\int_{0}^{T}\left(\int_{0}^{t} e^{-a(t-s)} f(s) d s\right)^{2} d t \leq \frac{\int_{0}^{T} f^{2}(t) d t}{a^{2}}
$$

Proof. Note that

$$
\left(\int_{0}^{t} e^{a s} f(s) d s\right)^{2}=2 \int_{0}^{t} \int_{0}^{s} e^{a s} e^{a u} f(u) f(s) d u d s
$$

If $U:=\int_{0}^{T}\left(\int_{0}^{t} e^{-a(t-s)} f(s) d s\right)^{2} d t$, then direct computations yield:

$$
\begin{gathered}
U=2 \int_{0}^{T} \int_{0}^{t} \int_{0}^{s} e^{-a(2 t-s-u)} f(u) f(s) d u d s d t= \\
2 \int_{0}^{T}\left(\int_{0}^{s}\left(\int_{s}^{T} e^{-2 a t} d t\right) e^{a u} f(u) d u\right) e^{a s} f(s) d s= \\
\int_{0}^{T}\left(\int_{0}^{s} a^{-1}\left(e^{-2 a s}-e^{2 a T}\right) e^{a u} f(u) d u\right) e^{a s} f(s) d s \leq \\
a^{-1} \int_{0}^{T}\left(\int_{0}^{s} e^{-a(s-u)} f(u) d u\right) f(s) d s \leq \\
a^{-1}\left(\int_{0}^{T} f^{2}(s) d s\right)^{1 / 2}\left(\int_{0}^{T}\left(\int_{0}^{s} e^{-a(s-u)} f(u) d u\right)^{2} d s\right)^{1 / 2}= \\
a^{-1}\left(\int_{0}^{T} f^{2}(s) d s\right)^{1 / 2} U^{1 / 2},
\end{gathered}
$$

and the result follows.

It is shown in the next lemma that under certain conditions on the operator $\mathcal{P}$ the asymptotic behavior of $\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t, K \rightarrow \infty$, is determined by that of $\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t$.
A.3. Lemma. If $\mathcal{P}$ is an essentially non-degenerate operator of order $p$ on $M$ and $p \geq m-d / 2$, then

$$
\begin{gather*}
\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t \asymp \sum_{k=1}^{N} l_{k}^{(p-m) / m}, K \rightarrow \infty  \tag{A.3}\\
\lim _{K \rightarrow \infty} \frac{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \eta(t)\right\|_{0}^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t}=0  \tag{A.4}\\
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \eta(t)\right\|_{0}^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t}=0  \tag{A.5}\\
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t}=1 . \tag{A.6}
\end{gather*}
$$

Proof.
Proof of (A.3). It follows from the independence of $\xi_{k}(t)$ for different $k$ that

$$
\begin{aligned}
& \mathbf{E} \sum_{k=1}^{K}\left|\psi_{k}(\mathcal{P} \xi(t))\right|^{2}=\mathbf{E} \sum_{k=1}^{K}\left|\sum_{n \geq 1} \xi_{n}(t)\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\right|^{2}= \\
& \sum_{k=1}^{K} \sum_{n \geq 1} \frac{1}{2 \theta_{1} l_{n}}\left(1-e^{-2 \theta_{1} l_{n} t}\right)\left|\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\right|^{2}
\end{aligned}
$$

Integration yields:

$$
\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t=\sum_{k=1}^{K} \sum_{n \geq 1} \frac{1}{2 \theta_{1} l_{n}}\left(T-\frac{1}{2 \theta_{1} l_{n}}\left(1-e^{-2 \theta_{1} l_{n} T}\right)\right)\left|\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\right|^{2}
$$

Since $l_{k} \rightarrow \infty$ and only asymptotic behavior, as $K \rightarrow \infty$, of all expressions is studied, it can be assumed that $1-e^{-2 \theta_{1} l_{k} T}>0$ for all $k$. Then the last equality and the definition of the norm $\|\cdot\|_{s}$ imply

$$
\begin{aligned}
& \frac{T}{2 \theta_{1}} \sum_{k=1}^{K}\left\|\mathcal{P}^{*} e_{k}\right\|_{-m}^{2}-C \sum_{k=1}^{K}\left\|\mathcal{P}^{*} e_{k}\right\|_{-2 m}^{2} \leq \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t \leq \\
& \frac{T}{2 \theta_{1}} \sum_{k=1}^{K}\left\|\mathcal{P}^{*} e_{k}\right\|_{-m}^{2} .
\end{aligned}
$$

Since $\mathcal{P}$ satisfies (3.4),

$$
\left\|\mathcal{P}^{*} e_{k}\right\|_{-m}^{2} \geq \varepsilon\left\|e_{k}\right\|_{p-m}^{2}-K\left\|e_{k}\right\|_{p-m-\delta}^{2}=\varepsilon \lambda_{k}^{2(p-m)}\left(1-(K / \varepsilon) \lambda_{k}^{-2 \delta}\right) .
$$

In addition, $\left\|\mathcal{P}^{*} e_{k}\right\|_{r}^{2} \leq C\left\|e_{k}\right\|_{r+p}^{2}$ and $\lambda_{k}=l_{k}^{1 /(2 m)}$. The result (A.3) follows.
Proof of (A.4). By assumptions,

$$
c:=\max (\operatorname{order}(\mathcal{A}), \operatorname{order}(\mathcal{B}), \operatorname{order}(\mathcal{M}))<2 m .
$$

By Lemma A.2,

$$
\int_{0}^{T}\left|\eta_{n}(t)\right|^{2} d t \leq \frac{1}{\left(\theta_{1} l_{n}\right)^{2}} \int_{0}^{T}\left|\psi_{n}\left(\left(\theta_{1} \mathcal{A}+\theta_{2} \mathcal{B}+\mathcal{M}\right) u(t)\right)\right|^{2} d t
$$

which implies that for every $r \in \mathbb{R}$

$$
\begin{aligned}
& \sum_{n \geq 1} \lambda_{n}^{2 r} \int_{0}^{T}\left|\psi_{n}(\mathcal{P} \eta(t))\right|^{2} d t \equiv \int_{0}^{T}\|\mathcal{P} \eta(t)\|_{r}^{2} d t \leq C \int_{0}^{T}\|\eta(t)\|_{r+p}^{2} d t \equiv \\
& \sum_{n \geq 1} \lambda_{n}^{2(r+p)} \int_{0}^{T}\left|\eta_{n}(t)\right|^{2} d t \leq C \int_{0}^{T}\|u(t)\|_{r-2 m+c+p}^{2}
\end{aligned}
$$

If $c_{1}:=2 m-c>0$ and $r=-x$ where $x=\max \left(0, d / 2+c_{1} / 2+p+c-3 m\right)$, then $-x-2 m+c+p=m-d / 2-c_{1} / 2$ and, by (2.4), $E \int_{0}^{T}\|u(t)\|_{-x-2 m+c+p}^{2}<\infty$. As a result, since $\lambda_{k} \asymp k^{1 / d}$,

$$
\begin{aligned}
& \frac{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \eta(t)\right\|_{0}^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t}=\frac{\sum_{n=1}^{K} \lambda_{n}^{-2 x} \lambda_{n}^{2 x} \mathbf{E} \int_{0}^{T}\left|\psi_{n}(\mathcal{P} \eta(t))\right|^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t} \leq \\
& \frac{C K^{2 x / d} \sum_{n \geq 1} \lambda_{n}^{-2 x} \mathbf{E} \int_{0}^{T}\left|\psi_{n}(\mathcal{P} \eta(t))\right|^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t} \leq \frac{C K^{2 x / d}}{\sum_{k=1}^{K} \lambda_{k}^{2(p-m)}} \rightarrow 0 \text { as } K \rightarrow \infty
\end{aligned}
$$

because if $p-m=-d / 2$, then $d / 2+c_{1} / 2+p+c-3 m=-c_{1} / 2<0$ so that $x=0$, while for $p-m>-d / 2$ the sum $\sum_{k=1}^{N} \lambda_{k}^{2(p-m)}$ is of order $N^{2(p-m) / d+1}$ and $2(p-m) / d+1>\left(d+2(p-m)-c_{1} / 2\right)=2 x / d$. This proves (A.4). Then (A.5) follows from (A.4) and the Chebychev inequality.

Proof of (A.6). There are two steps in the proof. Writing $X_{K} \overline{(t):=\| \Pi^{K} \mathcal{P} \xi(t)} \|_{0}^{2}$, the first step is to show that for all $t \in[0, T]$,

$$
\begin{equation*}
\operatorname{var}\left(X_{K}(t)\right) \leq C \sum_{k=1}^{K} \lambda_{k}^{4(p-m)} \tag{A.7}
\end{equation*}
$$

This will imply that (A.6) holds (the second step), i.e. that

$$
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T} X_{K}(t) d t}{\mathbf{E} \int_{0}^{T} X_{K}(t) d t}=1
$$

1). If $X_{K}^{M}(t):=\sum_{k=1}^{K}\left|\sum_{n=1}^{M} \xi_{n}(t)\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\right|^{2}$, then $X_{K}^{M}(t)$ is a quadratic form of the Gaussian vector $\left(\xi_{1}(t), \ldots, \xi_{M}(t)\right)$. The matrix of the quadratic form is $A=$ $\left[A_{n n^{\prime}}\right]_{n, n^{\prime}=1, \ldots, M}$ with

$$
A_{n n^{\prime}}=\sum_{k=1}^{K}\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\left(e_{n^{\prime}}, \mathcal{P}^{*} e_{k}\right)_{0}
$$

and the covariance matrix of the Gaussian vector is

$$
R=\operatorname{diag}\left(\frac{1-e^{-2 \theta_{1} l_{n} t}}{2 \theta_{1} l_{k}}, n=1, \ldots, M\right) .
$$

It is still assumed that $1-e^{-2 \theta_{1} l_{k} T}>0$ for all $k$.
Direct computations yield

$$
\mathbf{E} X_{K}^{M}(t)=\sum_{k=1}^{K} \sum_{n=1}^{M} \frac{1}{2 \theta_{1} l_{n}}\left(1-e^{-2 \theta_{1} l_{n} t}\right)\left|\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\right|^{2}=\operatorname{trace}(A R) .
$$

Analysis of the proof of (A.3) shows that for every $t \in[0, T]$ and $k=1, \ldots, K$ the series $\sum_{n \geq 1} \xi_{n}(t)\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}$ converges with probability one and in the mean square. Consequently,

$$
\begin{align*}
\lim _{M \rightarrow \infty} X_{K}^{M}(t) & =X_{K}(t) \quad(\mathbf{P}-\text { a.s. }) \\
\lim _{M \rightarrow \infty} \mathbf{E} X_{K}^{M}(t) & =\sum_{k=1}^{K} \sum_{n \geq 1} \mathbf{E}\left|\xi_{n}(t)\right|^{2}\left|\left(e_{n}, \mathcal{P}^{*} e_{k}\right)_{0}\right|^{2}=\mathbf{E} X_{K}(t) \tag{A.8}
\end{align*}
$$

Next,

$$
\begin{aligned}
& \operatorname{var}\left(X_{K}^{M}(t)\right)=2 \operatorname{trace}\left((A R)^{2}\right) \leq C \sum_{n, n^{\prime}} \frac{1}{l_{n} l_{n^{\prime}}} A_{n n^{\prime}}^{2}= \\
& \sum_{k, k^{\prime}=1}^{K}\left|\left(\tilde{\mathcal{P}} e_{k}, e_{k^{\prime}}\right)_{0}\right|^{2} \lambda_{k}^{4(p-m)} \leq \sum_{k=1}^{K}\left\|\tilde{\mathcal{P}} e_{k}\right\|_{0}^{2} \lambda_{k}^{4(p-m)} \leq C \sum_{k=1}^{K} \lambda_{k}^{4(p-m)},
\end{aligned}
$$

where $\tilde{\mathcal{P}}:=\mathcal{P} \Lambda^{-2 m} \mathcal{P}^{*} \Lambda^{2(m-p)}$ is a bounded operator in $\mathbb{H}^{0}$. After that, inequality (A.7) follows from (A.8) and the Fatou lemma:

$$
\begin{aligned}
& \operatorname{var}\left(X_{K}(t)\right)=\mathbf{E} \lim _{l \rightarrow \infty}\left|X_{K}^{M}(t)\right|^{2}-\left|\mathbf{E} \lim _{\lim _{\infty}} X_{K}^{M}(t)\right|^{2}= \\
& \mathbf{E} \lim _{M \rightarrow \infty}\left|X_{K}^{M}(t)\right|^{2^{M}}-\lim _{M \rightarrow \infty}\left|\mathbf{E} X_{K}^{M}(t)\right|^{2} \leq \liminf _{M \rightarrow \infty} \mathbf{E}\left|X_{K}^{M}(t)\right|^{2}-\lim _{M \rightarrow \infty}\left|\mathbf{E} X_{K}^{M}(t)\right|^{2} \leq \\
& \liminf _{M \rightarrow \infty} \operatorname{var}\left(X_{K}^{M}(t)\right) \leq C \sum_{k=1}^{K} \lambda_{k}^{4(p-m)} .
\end{aligned}
$$

2). If $Y_{K}:=\int_{0}^{T}\left(X_{K}(t)-\mathbf{E} X_{K}(t)\right) d t / \mathbf{E} \int_{0}^{T} X_{K}(t) d t$, then

$$
\frac{\int_{0}^{T} X_{K}(t) d t}{\mathbf{E} \int_{0}^{T} X_{K}(t) d t}=1+Y_{K}
$$

and

$$
\mathbf{E} Y_{K}^{2} \leq \frac{T \int_{0}^{T}\left(\operatorname{var}\left(X_{K}(t)\right) d t\right.}{\left(\mathbf{E} \int_{0}^{T} X_{K}(t) d t\right)^{2}} \leq C \frac{\sum_{k=1}^{K} \lambda_{k}^{4(p-m)}}{\left(\sum_{k=1}^{K} \lambda_{k}^{2(p-m)}\right)^{2}} \rightarrow 0 \quad \text { as } K \rightarrow \infty
$$

By the Chebychev inequality, $\mathbf{P}-\lim _{K \rightarrow \infty} Y_{K}=0$, which implies (A.6).
A.4. Corollary. If $\mathcal{P}$ is an essentially non-degenerate operator of order $p$ on $M$ and $p \geq m-d / 2$, then

$$
\begin{equation*}
\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|^{2} d t \asymp \frac{\varepsilon T}{2 \theta_{1}} \sum_{k=1}^{K} l_{k}^{(p-m) / m}, K \rightarrow \infty \tag{A.9}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t}{\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t}=1 \tag{A.10}
\end{equation*}
$$

Proof. By the inequality $|2 x y| \leq \epsilon x^{2}+\epsilon^{-1} y^{2}$, which holds for every $\epsilon>0$ and every real $x, y$,

$$
\begin{aligned}
& (1-\epsilon) \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t+\left(1-\frac{1}{\epsilon}\right) \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \eta(t)\right\|_{0}^{2} d t \leq \\
& \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} u(t)\right\|_{0}^{2} d t \leq \\
& (1+\epsilon) \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \xi(t)\right\|_{0}^{2} d t+\left(1+\frac{1}{\epsilon}\right) \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{P} \eta(t)\right\|_{0}^{2} d t .
\end{aligned}
$$

Since $\epsilon$ is arbitrary, (A.9) follows from (A.4) and (A.3). After that, (A.10) follows from (A.6).
A.5. Lemma. Assume that $\mathcal{B}$ is an elliptic operator of order $b>m-d / 2$. Then

$$
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), \mathcal{B} u(t)\right)_{0} d t}{\mathbf{E} \int_{0}^{T}\left(\Pi^{K}(\mathcal{L}+\mathcal{A}) u(t), \mathcal{B} u(t)\right)_{0} d t}=1
$$

Proof. With no loss of generality assume that $\mathcal{B}$ is bounded from below: for all $s \in \mathbb{R}$ there exist positive numbers $C_{1}, C_{2}, \delta$ so that the inequality

$$
\begin{equation*}
(\mathcal{B} f, f)_{s} \geq C_{1}\|f\|_{s+b / 2}^{2}-C_{2}\|f\|_{s+b / 2-\delta} \tag{A.11}
\end{equation*}
$$

holds for all $f \in \mathbf{C}^{\infty}(M)$; otherwise replace $\mathcal{B}$ by $-\mathcal{B}$. Direct computations show that $\mathbf{E} \int_{0}^{T}\left(\Pi^{K} \mathcal{L} \xi(t), \mathcal{B} \xi(t)\right)_{0} d t \asymp K^{b / d+1} ; \mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{A} u(t)\right\|_{0}^{2} d t \leq C K^{2(m-\delta) / d+1}, \delta>0 ;$ $\mathbf{E} \int_{0}^{T}\left\|\Pi^{K} \mathcal{L} \xi(t)\right\|_{0}^{2} d t \asymp K^{2 m / d+1}, \mathbf{E} \int_{0}^{T}\|\mathcal{B} \xi(t)\|_{0}^{2} d t \asymp K^{2(b-m) / d+1}$.
(The last two relations follow from Lemma A.3.) The Cauchy-Schwartz inequality then implies that the statement of the lemma will follow from the convergence

$$
\begin{equation*}
\mathbf{P}-\lim _{K \rightarrow \infty} \frac{\int_{0}^{T}\left(\Pi^{K} \mathcal{L} \xi(t), \mathcal{B} \xi(t)\right)_{0} d t}{\mathbf{E} \int_{0}^{T}\left(\Pi^{K} \mathcal{L} \xi(t), \mathcal{B} \xi(t)\right)_{0} d t}=1 \tag{A.12}
\end{equation*}
$$

It can be shown in the same way as in the proof of (A.6) that

$$
\operatorname{var}\left(\left(\Pi^{K} \mathcal{L} \xi(t), \mathcal{B} \xi(t)\right)_{0}\right) \leq C K^{2 b / d+1}
$$

for every $t \in[0, T]$ with $C$ independent of $t$. After that the Chebuchev inequality implies (A.12), which completes the proof of the lemma.

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