# LOCAL MATCHING OF RANDOM RESTRICTION MAPS 

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#### Abstract

Optical mapping is a new technique to generate restriction maps of DNA easily and quickly. DNA restriction maps can be aligned by comparing corresponding restriction fragment lengths. To relate, organize, and analyse these maps it is necessary to rapidly compare maps. The issue of the statistical significance of approximately matching maps then becomes central, as in BLAST with sequence scoring. In this paper, we study the approximation to the distribution of counts of matched regions of specified length when comparing two DNA restriction maps. Distributional results are given to enable us to compute $p$-values and hence to determine whether or not the two restriction maps are related. The key tool used is the Chen-Stein method of Poisson approximation. Certain open problems are described.


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## 1. Introduction

Before a genome is sequenced, restriction maps of the genome are often obtained. Restriction maps are examples of physical maps. The restriction map of the DNA sequence of an organism is a very useful tool for DNA sequencing and other genome studies. Restriction maps are aligned for many reasons including: constructing longer restriction maps by overlapping short maps, finding evolutionary relationships and, given genome restriction maps, locating smaller pieces of DNA in that genome. The basis of restriction map alignment is that, if two DNA sequences are identical, their restriction maps using the same set of enzymes are expected to be almost identical, which means they should have the same number of restriction sites and each ordered pair of restriction fragments should have almost the same length ('almost' is due to the experiment error in measuring the lengths of restriction fragments, detailed explanation for different kinds of error sources are described in Tang (2000a).

In 1987, Kohara et al. constructed an eight-enzyme restriction map of the entire genome of Escherichia coli. One key step in their strategy of construction is that they searched for overlapping pairs of clones by matching the clones' eight-enzyme restriction maps. Overlapping clones are detected when they match at more than 5 consecutive fragments. Lander and Waterman (1988) presented a mathematical analysis for physical mapping by fingerprinting random clones, and also evaluated different types of fingerprinting schemes. Their paper contains simplified calculations for the probability that random clones will be declared an overlap.

[^0]Waterman et al. (1984) first modelled the map alignment problem to study the evolution between homologous genes from closely related organisms. The goal is to align the maps, which is the so-called global alignment problem. An algorithm was provided to compute an optimal alignment of two maps. The algorithm allows for site indels as well as differences in distance between sites. Later, Waterman and Raymond (1987), in a study of geological strata matching, made a modification to the algorithm that handles one type of the restriction map data errors from experiments: closely spaced sites of the same enzyme are merged as a single site. Huang and Waterman (1992) extended the previous map comparison model to handle another type of data error: closely spaced sites for different enzymes are ordered incorrectly, and that gave a dynamic algorithm program. Rudd et al. (1990) used restriction map alignment software to align DNA sequence, genetic, and physical maps of $E$. coli to form an integrated genomic map, after which the integrated genomic map of $E$. coli was used to refine the genetic map and to locate newly sequenced or mapped genes. The restriction map alignment software considers restriction maps as strings analogous to DNA or protein sequences, except that two values, enzyme name and DNA base address, are associated with each position on the string.

A new technique to generate restriction maps of DNA, optical mapping, has been developed by David Schwartz et al. (1993). A single DNA molecule is stretched out and fixed to a surface. A restriction enzyme is added to cut the DNA sequence, and the cut sites are visualized as gaps and the lengths of fragments are estimated by an optical method (the DNA molecules are coated with a fluorochrome and imaged). Optical mapping can generate restriction maps easily and quickly. Schwartz et al. (1993) applied optical mapping to Saccharomyces cerevisiae, and Lin et al. (1999) obtained the whole-genome restriction map of Deinococcus radiodurans. Potentially, this method can rapidly produce restriction maps of megabases of DNA, possibly of genomes. To relate, organize, and analyse these maps it will be necessary to rapidly compare maps. Anantharaman et al. (1997) provided the first detailed model of the data produced by the optical mapping process. They formulated a statistical algorithm for the problem of producing optical maps and implemented the algorithm. Statistical issues of the significance of approximately matched maps then become central as they do in BLAST with sequence scoring.

The global matching of two random restriction maps has been studied in Tang (2000b). The probability that two random restriction maps match is very small. Looking at two restriction maps, there might be two segments of consecutive restriction fragments on the two restriction maps, respectively, that do match. A pair of segments of matched fragments is referred to as a matching region in this paper. The number of fragments in the matching region, which is called length of the matching region, varies from 1 to some large value. Obviously, the larger the length, the less chance such a matching region occurs at random. If there exists a matching region of a specified length, there might be a significant similarity between the two restriction maps. But how large should the length be to detect the significant similarity? Karlin et al. (1983) outlined such a study for nucleic acid and protein sequences. Later on, this statistical significance problem has been studied widely for DNA sequences (see Arratia et al. (1990), Karlin et al. (1990), Karlin and Altschul (1990), Waterman and Vingron (1994), and C. Neuhauser (1994)). Here we will study this problem for restriction maps. There is much similarity with DNA or protein sequence matching, but enough differences to challenge us. As with sequence matching, maps present their own set of difficulties.

We consider single-enzyme DNA restriction maps with the model as follows. The occurrences of cut sites along a DNA sequence is a Poisson process with rate $\lambda$, where $\lambda$ is determined by the specific pattern of the cut site. Hence, the fragment lengths are i.i.d., each fragment length following an exponential distribution with density function $\lambda \mathrm{e}^{-\lambda x}, x \geq 0$.

We consider two fragments equal if their lengths differ by no more than a constant $\sigma$ (which is usually small compared to $\lambda^{-1}$ ) and the probability of this event is denoted as $p$, which is later computed from the exponential distribution. We will study two types of matching regions here. One is a matching region with all the consecutive pairs matched in the region. We are interested in the longest matching region between two random restriction maps. Since base mutations and deletions occur in the evolution of DNA sequences, to enable us to reveal the relationship between DNA sequences even after these changes, we will study another model of matching regions by allowing a few mismatches in a matching region. The main goal is to find an approximation to the distribution of counts of matching regions of specified length. From those distributional results, we can compute the tail probability for a matching region of specified length or greater, and hence test whether or not the two restriction maps are related.

The outline of the paper is as follows. In Section 2, we give an introduction to the key tool used in the paper: the Chen-Stein method. We approximate the distribution of the counts of matching regions of specified length in Section 3, where only matched fragment pairs are allowed in matching regions. Also, we test the results using simulations. In Section 4, we extend the approximation for matching regions to allow a few mismatches. Finally, we discuss an unsolved problem in Section 5, which we term the merge-matching problem, similar to the indel-problem of sequence alignment.

## 2. The Chen-Stein Method of Poisson approximation

The basic method employed in this paper is the Chen-Stein method, which is a method used to approximate the distribution of occurrences of dependent events by the Poisson distribution. A brief introduction is given in this section. The method is based on the work by Stein (1972) and was developed by Chen (1975). It was generalized to a multivariate context by Arratia et al. (1989), and below, we will state a version of the Chen-Stein method following their paper.

Let $I$ be an arbitrary index set, and for $i \in I, X_{i}$ is an indicator function to indicate whether or not some event occurs. The total number of occurrences of events is

$$
W=\sum_{i \in I} X_{i} .
$$

The set of events $\left\{X_{i}\right\}_{i \in I}$ could be dependent. The Chen-Stein method is a general approach to approximate the distribution of $W$ by a Poisson distribution $Z$ via bounding the total variation distance between $W$ and $Z$. Let $h: \mathbb{Z}^{+} \rightarrow \mathbb{R}$, where $\mathbb{Z}^{+}=\{0,1,2, \ldots\}$, and write $\|h\|=$ $\sup _{k \geq 0}|h(k)|$. The total variation distance between $W$ and $Z$ is denoted by

$$
\|W-Z\|=\sup _{\|h\|=1}|\mathrm{E} h(W)-\mathrm{E} h(Z)|=2 \sup _{A \subset \mathbb{Z}^{+}}|\mathrm{P}(W \in A)-\mathrm{P}(Z \in A)| .
$$

Before we state the theorem, we present more notation used in the approximation. Let $J_{i}$ be an index set such that $j \notin J_{i}$ if $X_{j}$ is independent of $X_{i}$. The approximation is related to the first and second moments of $\left\{X_{i}\right\}_{i \in I}, b_{1}$ and $b_{2}$, which are defined as

$$
b_{1}=\sum_{i \in I} \sum_{j \in J_{i}} \mathrm{E}\left(X_{i}\right) \mathrm{E}\left(X_{j}\right),
$$

and

$$
b_{2}=\sum_{i \in I} \sum_{i \neq j \in J_{i}} \mathrm{E}\left(X_{i} X_{j}\right) .
$$

Theorem 2.1. Let $W$ be the number of occurrences of dependent events, and let $Z$ be a Poisson random variable with $\mathrm{E}(Z)=\mathrm{E}(W)=\lambda$. Then

$$
\|W-Z\| \leq 2\left(b_{1}+b_{2}\right) \frac{1-\mathrm{e}^{-\lambda}}{\lambda} \leq 2\left(b_{1}+b_{2}\right)
$$

and in particular

$$
\left|\mathrm{P}(W=0)-\mathrm{e}^{-\lambda}\right| \leq\left(b_{1}+b_{2}\right) \frac{1-\mathrm{e}^{-\lambda}}{\lambda}
$$

This theorem is a process version of the Poisson approximation which is useful when we have to use the entire process of indicators $\left\{X_{i}\right\}_{i \in I}$. If $b_{1}$ and $b_{2}$ are small, then $W$ will be approximately Poisson distributed with rate $\mathrm{E}(W)$. Thus, to establish the Poisson approximation, we should check that the quantities $b_{1}$ and $b_{2}$ are small.

## 3. Matching region with matched fragment pairs

As in the global matching problem, a restriction map is represented as a string of capital letters with indices, such as $A_{1} A_{2} \ldots A_{n}$. Each $A_{i}$ denotes the length of the $i$ th fragment in the restriction map in a fixed orientation and $n$ is the total number of fragments in the restriction map (on maps with several enzymes, the cut site can also carry the identity of the enzyme as well). A pair of fragments $A_{i}$ and $A_{j}$ are matched if their lengths differ by no more than a small constant $\sigma$; matching is denoted by $A_{i}=\nabla A_{j}$ in this paper. A matching region between two restriction maps consists of two series of contiguous restriction fragments from each of the two restriction maps that have the same number of fragments and in which each corresponding fragment pair matches (see Figure 1). The number of fragment pairs in the matching region is defined to be the length of the matching region. When two restriction maps are aligned locally, we are interested in the matching region with the maximum length observed between the two restriction maps. If a matching region of length greater than or equal to some test value $t$ is observed, can we conclude that there is a high similarity or relation between the two sequences? To answer the question, we wish to know the $p$-value of such an observation.

As is often used for the studies of restriction maps, the occurrences of cut sites along a DNA sequence is assumed to be a Poisson process of rate $\lambda$, which is used to denote the cutting rate along DNA sequence. Therefore, the length of a restriction fragment has an exponential distribution with mean $1 / \lambda$. The value of $\lambda$ depends on the cut site pattern and the distribution of nucleotides in the DNA sequences.

### 3.1. Main results

Let $\boldsymbol{A}=A_{1} A_{2} \ldots A_{n}$ and $\boldsymbol{B}=B_{1} B_{2} \ldots B_{m}$ denote two restriction maps from the same enzyme of length $n$ and $m$ respectively. We wish to find the local similarities between $\boldsymbol{A}$ and $\boldsymbol{B}$; that is, we are interested in finding the matching regions of specified length between $\boldsymbol{A}$ and $\boldsymbol{B}$.


Figure i: Example of a matching region $\left\{A_{2}={ }_{\nabla} B_{2}, A_{3}={ }_{\nabla} B_{3}, A_{4}={ }_{\nabla} B_{4}, A_{5}=\nabla B_{5}\right\}$ starting at $(2,2)$. The length of the matching region is 4 .

A matching region between $\boldsymbol{A}$ and $\boldsymbol{B}$ can start at any index pair $(i, j)$ for $1 \leq i \leq n$ and $1 \leq j \leq m$. For a test value $t$, we define the index set $I$ to be $\{(i, j): 1 \leq i \leq n-t+1,1 \leq$ $j \leq m-t+1\}$. For any index pair $v=(i, j) \in I$, it is possible to observe a matching region of length $t$ starting at $v$, which is $\left\{A_{i+k}={ }_{\nabla} B_{j+k}: k=0,1, \ldots, t-1\right\}$.

To state our results, we need a few more definitions. We define $Y_{\nu}$ to be an indicator function to denote the occurrence of the matching region of length $t$ starting at $v=(i, j)$, that is,

$$
Y_{\nu}=\mathbf{1}_{\left\{A_{i+k}=\nabla B_{j+k}: k=0,1, \ldots, t-1\right\}} .
$$

Thus, $Y_{v}=1$ denotes the occurrence of a matching region of length $t$ starting at $\nu$. The probability of observing such an occurrence can be easily calculated by the following argument. The probability that $A_{i+k}={ }_{\nabla} B_{j+k}$, for $k=0,1, \ldots, t-1$, is

$$
\mathrm{P}\left(Y_{\nu}=1\right)=\prod_{k=0}^{t-1} \mathrm{P}\left(A_{i+k}=\nabla B_{j+k}\right)=p^{t}
$$

since $A_{1}, \ldots, A_{n}$ and $B_{1}, \ldots, B_{m}$ have i.i.d. exponential distributions. Here, $p=1-\mathrm{e}^{-\lambda \sigma}$ is the probability of two random restriction fragments matching, and is computed later in Lemma 3.2. When the fragment pair immediately before the matching region matches, matching regions occur in clumps. To de-clump, we define $X_{v}$ to be the indicator function for the start of a new clump of matching region. Hence,

$$
X_{v}=Y_{v}, \quad \text { if } i=1 \text { or } j=1
$$

otherwise

$$
X_{v}=\mathbf{1}_{\left\{A_{i-1} \neq B_{j-1}, A_{i+k}=\nabla B_{j+k}: k=0,1, \ldots, t-1\right\}} .
$$

Therefore, it is easy to show that

$$
\mathrm{P}\left(X_{v}=1\right)= \begin{cases}p^{t}, & i=1 \text { or } j=1 \\ (1-p) p^{t}, & \text { otherwise }\end{cases}
$$

Let $W(t)=\sum_{v \in I} X_{v}$ denote the number of occurrences of de-clumped matching regions and $S_{n, m}$ denote the length of the longest matching region between $\boldsymbol{A}$ and $\boldsymbol{B}$. We will prove the following theorem, where we set

$$
\lambda_{n, m}(t)=[(n+m-2 t+1)+(n-t)(m-t)(1-p)] p^{t}
$$

and define

$$
n \vee m=\max \{n, m\} .
$$

Theorem 3.1. Let $\boldsymbol{A}$ and $\boldsymbol{B}$ be two random restriction maps of length $n$ and $m$ respectively, as defined above, and $W(t)$ be the number of de-clumped matching regions of length $t$ between $\boldsymbol{A}$ and $\boldsymbol{B}$. Then

$$
\mathrm{E}(W(t))=\lambda_{n, m}(t)
$$

Let $b_{1}$ and $b_{2}$ be as in Section 2. Then

$$
\begin{aligned}
\left|\mathrm{P}(W(t)=0)-\mathrm{e}^{-\lambda_{n, m}(t)}\right| \leq & b_{1}+b_{2} \\
\leq & 2 \lambda_{n, m}(t)(2 t-1)(n \vee m) p^{t} \\
& +n m\left(2(2 t-1)(n \vee m) p^{(3 / 2+3 c) t}+(2 t-1)^{2} p^{(1+2 c) t}\right),
\end{aligned}
$$

since

$$
b_{1} \leq 2 \lambda_{n, m}(t)(2 t-1)(n \vee m) p^{t}
$$

and

$$
b_{2} \leq n m\left(2(2 t-1)(n \vee m) p^{(3 / 2+3 c) t}+(2 t-1)^{2} p^{(1+2 c) t}\right)
$$

The expected value of $W(t)$ can easily be derived as follows. Since

$$
\mathrm{E}(W(t))=\sum_{v \in I} \mathrm{E}\left(X_{v}\right)=\sum_{v \in I} \mathrm{P}\left(X_{v}=1\right)
$$

and there are $(n-t+1)+(m-t+1)-1$ distinct starting indices in $I$ with $i=1$ or $j=1$ and $(n-t)(m-t)$ distinct starting indices in $I$ with $i>1$ and $j>1$. The proof for the second result in Theorem 3.1 is the main goal in the next subsection.

From this theorem, we can derive a corollary to enable us to compute the tail probability of $S_{n, m}$ approximately. Before we start our study of approximating the tail probability of $S_{n, m}$, we present an asymptotic result. Arratia and Waterman (1985) proved for sequence matching that

$$
\lim _{n, m \rightarrow \infty} \frac{S_{n, m}}{\log _{1 / p}((1-p) n m)}=1, \quad \text { with probability } 1
$$

when $n=m$. By the same argument, they obtain the same result even if $n \neq m$, when the growth rate of $n$ and $m$ satisfies certain conditions.

The second result of Theorem 3.1 can be formulated under some conditions about the relative growth rate of $n, m$ and $t$. Suppose that the growth rate of $n$ and $m$ follows

$$
\frac{\log (n)}{\log (n m)} \rightarrow \rho>0
$$

Then $t$ can be scaled appropriately with $n$ and $m$ so that $\lambda_{n, m}(t)$ stays bounded away from 0 and $\infty$. Actually, from the asymptotic property of $S_{n, m}$, setting $t=\log _{1 / p}((1-p) n m)+s$ will keep $\lambda_{n, m}(t)$ between 0 and $\infty$. We will be more specific on how to choose the relative growth rate at the end of Subsection 3.2. Using this growth rate, we will approximate the distribution of $W(t)$ by a Poisson distribution that has the same expected value as $W(t)$ and then derive the probability of $W(t)=0$ when $n, m, t \rightarrow \infty$. Thus, we obtain the following corollary of Theorem 3.1.
Corollary 3.1. Under the conditions on the relative growth rate of $n, m$ and described above, there exists constants $C, \gamma>0$, such that

$$
\left|\mathrm{P}\left(S_{n, m}<t\right)-\mathrm{e}^{-\lambda_{n, m}(t)}\right|=\left|\mathrm{P}(W(t)=0)-\mathrm{e}^{-\lambda_{n, m}(t)}\right| \leq C(\log n m)^{-\gamma}
$$

### 3.2. Approximate distribution for $\boldsymbol{W}(\boldsymbol{t})$

To establish the Poisson estimate for $W(t)$, we use the Chen-Stein method as introduced in Section 2. The first and second moments of $W(t)$ should be well behaved to achieve our goal. Therefore, we need find bounds for $b_{1}$ and $b_{2}$ in the method and show their convergence to 0 as $n, m \rightarrow \infty$. As in Theorem 2.1, for a given $X_{v}$, where $v \in I$, let $J_{v}$ denote the set of potential dependence, i.e.

$$
J_{v}=\left\{\mu=\left(i^{\prime}, j^{\prime}\right) \in I:\left|i-i^{\prime}\right| \leq t \text { or }\left|j-j^{\prime}\right| \leq t\right\}
$$



Figure 2: The four arms are $D_{2}$, the central part is $D_{1}$.


Figure 3: Solid lines and dashed lines represent two dependent matching regions of length $5, Y_{(1,1)}$ and $Y_{(4,2)}$, respectively. The two matching regions separate all the involved fragments to two 2-components and two 5-components. They are $\left\{A_{1}={ }_{\nabla} \quad B_{1}\right\},\left\{A_{8}={ }_{\nabla} B_{6}\right\},\left\{A_{2}={ }_{\nabla} B_{2}, B_{2}=\nabla A_{4}, A_{4}=\nabla B_{4}\right.$,

$$
\left.B_{4}={ }_{\nabla} A_{6}\right\} \text { and }\left\{A_{3}={ }_{\nabla} B_{3}, B_{3}={ }_{\nabla} A_{5}, A_{5}={ }_{\nabla} B_{5}, B_{5}=\nabla A_{7}\right\}
$$

If $\mu \in J_{\nu}$, the two matching regions starting at $\mu$ and $\nu$ share common restriction fragments, and so $X_{\nu}$ and $X_{\mu}$ can be dependent; otherwise, if $\mu \notin J_{v}$, the two matching regions share no common fragments, and so $X_{\nu}$ and $X_{\mu}$ are independent.

The estimation of $b_{1}$ is easily found to be

$$
\begin{aligned}
b_{1} & =\sum_{v \in I} \sum_{\mu \in J_{v}} \mathrm{E}\left(X_{\nu}\right) \mathrm{E}\left(X_{\mu}\right) \leq \sum_{v \in I} \mathrm{E}\left(X_{v}\right)(2 t+1)(n+m) p^{t} \\
& \leq \sum_{v \in I} \mathrm{E}\left(X_{v}\right) 2(2 t+1)(n \vee m) p^{t}=2 \lambda_{n, m}(t)(2 t+1)(n \vee m) p^{t} .
\end{aligned}
$$

The estimation of the upper bound of $b_{2}$ is not as straightforward as the estimation of $b_{1}$. We notice that $J_{v}$ consists of a horizontal and a vertical strip. We divide $J_{v}$ into two disjoint subsets (see Figure 2). Let

$$
D_{1}=\left\{\gamma=\left(i^{\prime}, j^{\prime}\right) \in I:\left|i-i^{\prime}\right| \leq t \text { and }\left|j-j^{\prime}\right| \leq t\right\}
$$

be the intersection of the two strips and $D_{2}=J_{v}-D_{1}$.
We estimate $b_{2}$ by computing upper bounds for $\mathrm{E}\left(X_{\nu} X_{\mu}\right)$ for $\mu \in D_{i}, i=1,2$, separately. Since $X_{\nu} \leq Y_{\nu}$, an upper bound for $\mathrm{E}\left(Y_{\nu} Y_{\mu}\right)$ is also an upper bound for $\mathrm{E}\left(X_{\nu} X_{\mu}\right)$. Here we only study the bound for $\mathrm{E}\left(X_{\nu} X_{\mu}\right)$ when $i_{\nu}-i_{\mu} \neq j_{\nu}-j_{\mu}$, since $X_{\nu}=X_{\mu}=0$ when $i_{\nu}-i_{\mu}=j_{\nu}-j_{\mu}$ by our definition of de-clumping. In the following figures, we represent a fragment as a node and a solid or dashed line connecting two matched fragments. All the fragments involved in the two matching regions are separated into independent connected components (see Figure 3). We define the size of a component as the number of fragments


Figure 4: Full connected matching regions.
(nodes) involved in the component; an $r$-component is a component of size $r$. The distinct components do not share any common fragments, so they are independent. The probability that $Y_{\nu}=Y_{\mu}=1$ can be written as the product of the probabilities of the occurrence of those independent components.

The following lemma about the components defined by two matching regions will be useful in estimating the upper bound for $b_{2}$. It is the same result as in sequence matching, but we include the proof for completeness.

Lemma 3.1. Let $Y_{\nu}, Y_{\mu}$ be variables defined for matching regions as above, that is, $\mu \in J_{\nu}$, and $i_{\nu}-i_{\mu} \neq j_{\nu}-j_{\mu}$. All the fragments involved in the two matching regions are separated into independent connected components. Let $x_{r}, r=2, \ldots, 2 t+1$, denote the number of $r$-components, then

$$
\sum_{r=2}^{2 t+1} x_{r}(2(r-1))=4 t
$$

Proof. It is obvious that the size of a component is at least 2; the largest component formed from two matching regions of length $t$ is that where all the fragments in the two matching regions are connected to one component (see Figure 4) and the size is $2 t+1$.

We count the number of fragments involved as follows. If a fragment appears in one matching region, it is counted once; if it appears in both matching regions, it is counted twice. Since there are $2 t$ fragments in each matching region, there is a total of $4 t$ fragments. For each $r$-component, the middle $r-2$ fragments appear in both matching regions and are counted twice; the two end fragments appear in only one matching region and are counted once. So an $r$-component contains $2+2(r-2)=2(r-1)$ counted fragments. Summing over all the components, we obtain

$$
\sum_{r=2}^{2 t-1} x_{r}(2(r-1))=4 t
$$

Let $p_{r}$ denote the following probability,

$$
p_{r}=\mathrm{P}\left(A_{1}={ }_{\nabla} A_{2} \text { and } A_{2}={ }^{2} A_{3} \text { and } \ldots A_{r-1}=\nabla A_{r}\right),
$$

where $A_{i}, i=1, \ldots, r$, are i.i.d. and exponentially distributed with density function $\lambda \mathrm{e}^{-\lambda x}$. We use $p_{r}$ in the calculation of $\mathrm{E}\left(Y_{\nu} Y_{\mu}\right)$, but it is difficult to compute. Since we only need to estimate the upper bound of $\mathrm{E}\left(Y_{\nu} Y_{\mu}\right)$, we give the following two lemmas for a similar purpose to that of Lemma 11.5 in Waterman (1995). The proof of the two lemmas are given in the appendices.
Lemma 3.2. Let $p_{3}$ denote the probability of observing a 3-component, then $p_{3}=p^{3 / 2+3 c}$, for a constant $0<c<\frac{1}{6}$.


Figure 5: There are $y=42$-components and $x=33$-components. The length of matching region is 5 , and $4 x+2 y=20=4 t$.

Using Lemma 3.2, $p_{r}$ can be bounded through $p$ for any $r \geq 2$.
Lemma 3.3. For any $r \geq 2$, there is

$$
p_{r} \leq p^{(1 / 2+c)(r-1)}
$$

where $c$ is as in Lemma 3.2.
Now, we consider the upper bound for $b_{2}$. First, we will consider $\mu \in D_{2}$ (see Figure 2). In this case, there are only 2-components and 3-components (see Figure 5), since no two matched fragments in the matching region starting at $v$ are involved in the matching region starting at $\mu$ and vice versa.

Let $x$ denote the number of 3-components and $y$ denote the number of 2-components; then $4 x+2 y=4 t$. Since $3 c<\frac{1}{2}$, we have $3 c-\frac{1}{2}<0$ and $\left(3 c-\frac{1}{2}\right) x>\left(3 c-\frac{1}{2}\right) t$ for $x \leq t$. Thus,

$$
\begin{aligned}
\mathrm{E}\left(Y_{\nu} Y_{\mu}\right) & =p^{y} p_{3}^{x}=p^{2 t-2 x}\left(p^{3 / 2+3 c}\right)^{x}=p^{2 t+(3 c-1 / 2) x} \\
& \leq p^{2 t+(3 c-1 / 2) t}=p^{(3 / 2+3 c) t}, \quad \text { for } \mu \in D_{2} .
\end{aligned}
$$

Next, we consider $\mu \in D_{1}$. In this case, the size of component varies from 2 to $2 t-$ 1. If $x_{r}$ denotes the number of $r$-components formed from the two matching regions, then $\sum_{r=2}^{2 t-1} x_{r}(2(r-1))=4 t$. We write

$$
\begin{aligned}
\mathrm{E}\left(Y_{\nu} Y_{\mu}\right) & =p^{x_{2}} p_{3}^{x_{3}} \cdots p_{2 t-1}^{x_{2 t-1}} \leq \prod_{r=2}^{2 t-1}\left(p^{(1 / 2+c)(r-1)}\right)^{x_{r}} \\
& =p^{(1 / 2+c) \sum_{r=2}^{2 t-1}(r-1) x_{r}}=p^{(1 / 2+c) 2 t}=p^{(1+2 c) t}, \quad \text { for } \mu \in D_{1}
\end{aligned}
$$

The inequality is due to Lemma 3.2, $p_{r} \leq p^{(1 / 2+c)(r-1)}$, for $r \geq 2$.
We have bounded $\mathrm{E}\left(Y_{\nu} Y_{\mu}\right)$ for $\mu$ in $D_{1}$ and $D_{2}$ separately. From the definition of $D_{1}$, we know that $\left|D_{1}\right|=(2 t+1)^{2}$ and $\left|D_{2}\right|=(2 t+1)(n+m)$. To obtain the bound for $b_{2}$ we combine the above results:

$$
\begin{aligned}
b_{2} & =\sum_{\nu} \sum_{\nu \neq \mu \in J_{v}} \mathrm{E}\left(X_{\nu} X_{\mu}\right) \leq \sum_{\nu} \sum_{\nu \neq \mu \in J_{v}} \mathrm{E}\left(Y_{\nu} Y_{\mu}\right) \\
& =\sum_{\nu}\left(\sum_{D_{2}}+\sum_{D_{1}}\right) \mathrm{E}\left(Y_{\nu} Y_{\mu}\right) \\
& \leq n m\left((2 t+1)(n+m) p^{(3 / 2+3 c) t}+(2 t+1)^{2} p^{(1+2 c) t}\right) \\
& \leq n m\left(2(2 t+1)(n \vee m) p^{(3 / 2+3 c) t}+(2 t+1)^{2} p^{(1+2 c) t}\right) .
\end{aligned}
$$

Combining with the bound for $b_{1}$, we obtain

$$
b_{1}+b_{2} \leq 2 \lambda(2 t+1)(n \vee m) p^{t}+n m\left(2(2 t+1)(n \vee m) p^{(3 / 2+3 c) t}+(2 t+1)^{2} p^{(1+2 c) t}\right)
$$

We have proved Theorem 3.1. To derive Corollary 3.1, we need to show the bound for $b_{1}+b_{2}$ goes to zero as $n, m, t \rightarrow \infty$ under the relative growth rate of $n$ and $m$

$$
\frac{\log (n)}{\log (n m)} \rightarrow \rho>0 \quad \text { and } \quad \frac{\log (m)}{\log (n m)} \rightarrow 1-\rho>0
$$

and make a choice of $t$ such that $\lambda_{n, m}(t) \in(0, \infty)$. The expected value of $W(t)$ has already been calculated and is denoted by $\lambda_{n, m}(t)$. Obviously,

$$
\lambda_{n, m}(t) \approx_{\infty} n m p^{t}
$$

where $\approx_{\infty}$ means the asymptotic equality of the logarithms of the two quantities, that is,

$$
Q_{1} \approx_{\infty} Q_{2}
$$

implies that

$$
\frac{\log \left(Q_{1}\right)}{\log \left(Q_{2}\right)} \rightarrow 1, \quad \text { as } n, m \rightarrow \infty
$$

where $Q_{1}$ and $Q_{2}$ are two quantities depending on $n$ and $m$. From the asymptotic equality between $Q_{1}$ and $Q_{2}$, it is easy to derive that $Q_{1} \rightarrow 0$ as $Q_{2} \rightarrow 0$ for $n, m \rightarrow \infty$ and vice versa.

If $\rho \geq \frac{1}{2}$, then $(n \vee m) \approx_{\infty} n \approx_{\infty}(n m)^{\rho}$, and thus

$$
\begin{aligned}
b_{1} & \approx_{\infty} 2 \lambda_{n, m}(t)(2 t+1)(n \vee m) p^{t} \\
& \approx_{\infty} \lambda_{n, m}(t)(2 t+1)(n m)^{\rho} p^{t} \\
& \approx_{\infty} \lambda_{n, m}^{2}(t)(2 t+1)(n m)^{\rho-1},
\end{aligned}
$$

and

$$
\begin{aligned}
b_{2} & \approx_{\infty}(2 t+1)(n m)^{1+\rho} p^{(3 / 2+3 c) t}+(2 t+1)^{2}(n m) p^{(1+2 c) t} \\
& \approx_{\infty} \lambda_{n, m}^{(3 / 2+3 c)}(t)(2 t+1)(n m)^{\rho-(1 / 2)-3 c}+\lambda_{n, m}^{(1+2 c)}(t)(2 t+1)^{2}(n m)^{-2 c}
\end{aligned}
$$

To ensure that these bounds go to 0 , the following conditions should be satisfied:

$$
\rho-1<0, \quad \rho-\frac{1}{2}-3 c<0, \quad \text { and } \quad-2 c<0
$$

The first and third inequalities are satisfied automatically, so $\rho$ should assume values to satisfy the second inequality, and we obtain $\rho<\frac{1}{2}+3 c$. When $\rho \leq \frac{1}{2},(n \vee m) \approx_{\infty} m \approx_{\infty}$ $(n m)^{1-\rho}$, and repeat the above argument, to obtain $\rho>\frac{1}{2}-3 c$. From the analysis, if we let $\rho \in\left(\frac{1}{2}-3 c, \frac{1}{2}+3 c\right)$, and $t$ be chosen so that $\lambda_{n, m}(t)$ is bounded away from 0 and $\infty$, then $b_{1}+b_{2} \rightarrow 0$ when $n, m, t \rightarrow \infty$. We conclude that $W(t)$ is approximately distributed as a Poisson random variable with mean $\lambda_{n, m}(t)$. Since

$$
\left|\mathrm{P}(W(t)=0)-\mathrm{e}^{-\lambda_{n, m}(t)}\right| \leq\left(b_{1}+b_{2}\right) \frac{1-\mathrm{e}^{-\lambda_{n, m}(t)}}{\lambda_{n, m}}(t) \leq b_{1}+b_{2},
$$



Figure 6: Comparison of $\lambda_{600,600}(t)$, the expected number of $W(t)$, of our calculated formula and simulation results with 2 standard deviation.
and letting $t=\log _{1 / p}(n m)+s, s>0$, to keep $\lambda_{n, m} \in(0, \infty)$, there exists some constants $C>0$ and $\gamma>0$ such that

$$
b_{1}+b_{2} \leq C(\log n m)^{-\gamma}
$$

under the relative growth rate of $n, m$ and $t$ as discussed in the above asymptotic study. Therefore,

$$
\left|\mathrm{P}(W(t)=0)-\mathrm{e}^{-\lambda_{n, m}(t)}\right| \leq C(\log n m)^{-\gamma} .
$$

Finally, we wish to find the $p$-value of $S_{n, m}$ given a test value $t$. If $W(t)=0$, then there is no matching region of length $t$ between $\boldsymbol{A}$ and $\boldsymbol{B}$, which implies that there is no matching region of length greater than or equal to $t$ between the two restriction maps, that is, $S_{n, m}<t$; on the other hand, $S_{n, m}<t$ implies that there is no matching region of length $t$ between $\boldsymbol{A}$ and $\boldsymbol{B}$, and thus $W(t)=0$. We conclude that the $p$-value of $S_{n, m}$ is the same as $1-\mathrm{P}(W(t)=0)$, so

$$
\left|\mathrm{P}\left(S_{n, m}<t\right)-\mathrm{e}^{-\lambda_{n, m}(t)}\right|=\leq C(\log n m)^{-\gamma} .
$$

### 3.3. Testing the model

In the previous subsection, we showed that $W(t)$ is approximately Poisson distributed. We will do tests simulating restriction map matching to show how well the distribution is approximated. Our simulation tests $\lambda_{n, m}(t)$ and the distribution of $W(t)$ compared with the Poisson distribution.

We use $n=m=600, \sigma=200$ and $\lambda=1 / 1024$ (corresponding to a 5 -letter cutter). In our simulation, 5000 pairs of random restriction maps are compared. For each comparison, we count the number of de-clumped matching regions of some specified length $t$, where $t$ assumes values $8,9,10,11$ and 12 separately. The average number of de-clumped matching regions of length $t$ for the 5000 comparisons is computed and compared with the values from our formula for $\lambda_{n, m}(t)$. From Figure 6, we see that $\lambda_{n, m}(t)$ agrees with the simulation results very well, which is due to the fact that $\lambda_{n, m}(t)$ is the exact analytical expected value of $W(t)$ under our assumptions.


Figure 7: Poisson approximation for the distribution of $W(t)$, for $t=7,8,9,10$. Here, * denotes the empirical distribution of $W(t)$ from our simulation. The vertical bar denotes the Poisson distribution with mean value $\lambda_{600,600}(t)$.

To test the distribution of $W(t)$, we collect the lengths of matching regions for many (5000) matchings of restriction maps of length $n=m=600$. Then, for a given $t$, we count the number of compared restriction map pairs with maximum matching regions of length over $t$. In general, for larger $t$ the Poisson approximation is better. To show how well $W(t)$ is approximated by the Poisson distribution, we compare the empirical distribution of $W(t)$ with the Poisson distribution $Z$ with the same expected value $\lambda_{n, m}(t)$. From Figure 7, we see that the larger $t$ is, the better the empirical distribution is approximated by Poisson.

## 4. Matching regions with a few mismatches

In the evolution of DNA sequences, when deletions occur (here we refer to large segment deletions, which reduce the length of a restriction fragment), the restriction map of the DNA sequence with deletions is quite different from the restriction map of the original DNA sequence. If the deletion occurs within a restriction fragment, i.e. between two adjacent cut sites, then the lengths of the two restriction fragments in the two DNA sequences do not match (see Figure 8). In this case, even if the two DNA sequences are highly related, it might not be reported since the deletion shortens the length of matching region between the two restriction maps.

### 4.1. The expected counts of matching regions

To be able to reveal highly related restriction maps even if there are large segment deletions within single restriction fragments, we allow a few mismatches in a matching region. Instead of the model of exact matching, in which all fragment pairs in a matching region are matched, we study the model of imperfect match, in which we consider a long run of matches of length


Figure 8: The occurrence of a segment deletion in map 1 causes $A_{6}$ not to match $B_{6}$.


Figure 9: Example of a matching region of length 4 with 1 mismatch.
$t$ except for $k$ mismatches, i.e.

$$
\left\{A_{i+r}={ }_{\nabla} B_{j+r}: r=0, \ldots, t-1, \text { except for } k \text { mismatches }\right\}
$$

as a matching region of length $t$ (see Figure 9), and it is called a matching region of type $(t ; k)$, where $k<t$. Also, we call the $t$ consecutive fragment pairs a window of size $t$ starting at $(i, j)$. For a fixed $k$, we wish to find the longest window with no more than $k$ mismatches. Let $S_{n, m}^{k}$ denote the maximum length of a window between $\boldsymbol{A}$ and $\boldsymbol{B}$ including at most $k$ mismatches. We wish to find the distribution of $S_{n, m}^{k}$ in order to estimate the $p$-value. We study the problem for fixed $t$ first.

When looking at a window of size $t$, the more matching pairs we observe the higher the similarity is. We begin by finding the probability of observing $k$ mismatches in a window of size $t$. As usual, $I=\{(i, j): 1 \leq i \leq n-t+1,1 \leq j \leq m-t+1\}$ denotes the index set. To begin with, we consider fixed $t$ and $k$, and refer to matching regions without mentioning type $(t ; k)$. We give some definitions below that are used in the proof. Let $Y_{\nu}$ be the indicator function for indicating the occurrence of a matching region starting at $v \in I$. (Remember that $Y_{\nu}$ actually depends on $k$ in this section. For simplicity, we ignore $k$ in all the notations.) Since we allow $k$ mismatches in a matching region, there are many possible matchings starting at $v$ of the same type. Let $Y_{1}^{v}, Y_{2}^{v}, \ldots, Y_{K_{v}}^{v}$ be indicator functions of all possible matchings starting at $v \in I$; then

$$
\begin{aligned}
Y_{v} & =\mathbf{1}_{\left\{Y_{1}^{v}=1 \text { or } Y_{2}^{v}=1 \text { or } \ldots \text { or } Y_{K_{v}}^{v}=1\right\}} \\
& =\mathbf{1}_{\left\{A_{i+r}=\nabla B_{j+r}: r=0, \ldots, t-1 \text { except for } k \text { mismatches }\right\}},
\end{aligned}
$$

where $K_{\nu}$ is the number of all possible distinct matchings starting at $v$. Clearly,

$$
K_{v}=\binom{t}{k} \leq t^{k}
$$

which is a constant for all $v \in I$.


Figure io: Two highly correlated matching regions.

In each possible matching region, there are $t-k$ matching pairs and $k$ mismatches. It is easy to calculate the probability $\mathrm{P}\left(Y_{i}^{v}=1\right)=p^{t-k}(1-p)^{k}$. Let $p_{t, k}$ denote the probability that there is at least one matching region starting at position $v=\left(i_{v}, j_{v}\right) \in I$ with $k$ mismatches, i.e. $p_{t, k}=\mathrm{P}\left(Y_{\nu}=1\right)$. For $1 \leq i \neq j \leq K_{v}, Y_{i}^{v}=Y_{j}^{v}=1$ implies there is an $0 \leq l<t$ with $A_{i_{\nu}+l}={ }_{\nabla} B_{j_{\nu}+l}$ in one matching region and $A_{i_{\nu}+l} \neq B_{j_{\nu}+l}$ in the other one, which is a contradiction. Therefore, the events $\left\{Y_{i}^{\nu}\right\}_{i=1}^{K_{\nu}}$ are mutually exclusive, and we obtain

$$
\begin{aligned}
p_{t, k} & =\mathrm{P}\left(\left\{A_{i+r}=\nabla B_{j+r}: r=0,1, \ldots, t-1, \text { except for } k \text { mismatches }\right\}\right) \\
& =\sum_{l=0}^{K_{v}} \mathrm{P}\left(Y_{l}^{v}=1\right)=\binom{t}{k}(1-p)^{k} p^{t-k}
\end{aligned}
$$

which is also $\mathrm{E}\left(Y_{\nu}\right)$. The two matching regions starting at $v=\left(i_{\nu}, j_{\nu}\right) \in I$ and $\mu=\left(i_{\mu}, j_{\mu}\right) \in I$ and $\mu \neq v$, if $i_{\nu}-i_{\mu}=j_{\nu}-j_{\mu}$ and $\left|i_{v}-i_{\mu}\right|<t$, are highly correlated (see Figure 10) since they share $t-\left|i_{\nu}-i_{\mu}\right|$ common compared fragment pairs in the two windows. Thus, the matching regions tend to occur in clumps.

To be able to obtain a Poisson approximation, we should count the clumps and define the indicator function that a clump begins at $v$ to be

$$
X_{v}=Y_{v}\left(1-Y_{v-1}\right)\left(1-Y_{v-2}\right) \cdots\left(1-Y_{v-t+1}\right)
$$

where $v-l$, for $l=1, \ldots, t-1$, is the index pair $\left(i_{v}-l, j_{v}-l\right)$. When $i_{v}-l<1$ or $j_{v}-l<1$, we always have $Y_{\nu-l}=0$. To simplify the proof of the next lemma, we neglect the edge condition and set $I^{\prime}=\{(i, j): t-1<i<n-t+1, t-1<j<m-t+1\}$. We state a result for approximating the expected value of $X_{v}, v \in I^{\prime}$, by the expected value of $Y_{v}$. The proof for this lemma is almost the same as the proof of a similar lemma in Arratia et al. (1990) and is therefore omitted.

Lemma 4.1. Let $p<a=(t-k) / t \leq 1$, for $v \in I^{\prime}$

$$
a-p \leq \frac{\mathrm{E}\left(X_{v}\right)}{\mathrm{E}\left(Y_{v}\right)} \leq(a-p)+C(k) t^{k} p^{t}
$$

where $C(k)$ is a positive constant depending on $k$ and $p$.
For fixed $k, C(k) t^{k} p^{t} \rightarrow 0$ as $t \rightarrow \infty$, so $\mathrm{E}\left(X_{v}\right) \rightarrow(a-p) \mathrm{E}\left(Y_{v}\right)$ when $t$ goes to infinity. For large $t$ we can use $(a-p) \mathrm{E}\left(Y_{v}\right)$ to approximate $\mathrm{E}\left(X_{v}\right)$.


Figure in: Solid lines and dashed lines each represent two matching regions of length $t=4$ and $k=1$. There are $x_{2}=22$-components, $x_{3}=23$-components and 2 mismatches in total. Therefore,

$$
2 \times 2+2(2(3-1))+4 \times 1=16=4 t .
$$

Theorem 4.1. Let $W(t, k)=\sum_{v \in I} X_{v}$ be the number of de-clumped matching regions of type $(t ; k)$. We have

$$
1 \leq \frac{\mathrm{E}(W(t, k))}{e_{t, k}} \leq 1+\frac{C(k) t^{k} p^{t}}{a-p}+\frac{(n+m-2 t+2)(t-1)}{(a-p)(n-2 t+2)(m-2 t+2)}
$$

where $e_{t, k}=\sum_{v \in I^{\prime}}(a-p) \mathrm{E}\left(Y_{v}\right)=(a-p)(n-2 t+2)(m-2 t+2) \mathrm{E}\left(Y_{v}\right)$.
The proof for this theorem is quite straightforward (the extra term in the upper bound is from end effects). Thus, we can approximate $\mathrm{E}(W(t, k))$ by neglecting the edge conditions. With this approximation, we state the following distribution approximation for $W(t, k)$.
Theorem 4.2. Let $W(t, k)=\sum_{v \in I} X_{v}$ be the number of de-clumped matching regions of type $(t ; k)$ and $\lambda_{t, k}=\mathrm{E}(W(t, k))$. Then $b_{1}$ and $b_{2}$ for $\left\{X_{\nu}\right\}_{v \in I}$ are bounded as

$$
\begin{aligned}
\left|\mathrm{P}(W(t, k)=0)-\mathrm{e}^{-\lambda_{t, k}}\right| \leq & b_{1}+b_{2} \\
\leq & 2(2 t+1) \lambda_{t, k}(n \vee m) p_{t, k} \\
& +n m(2 t+1) t^{2 k}\left(C_{k}(n+m) p^{(3 / 2+3 c) t}+D_{k}(2 t+1) p^{(1+2 c) t}\right)
\end{aligned}
$$

We can approximate $\lambda_{t, k}$ by $e_{t, k}$ in Theorem 4.1 when $t$ is large. The distribution of $W(t, k)$ will be approximated by the Poisson distribution using the Chen-Stein method, and then we derive the estimation of the probability that $W(t, k)=0$ from the distributional result. To approximate the distribution of $W(t, k)$, we need to show that the two quantities $b_{1}$ and $b_{2}$ are small when $n, m$ are big. The proof for this theorem is similar to the proof of the exact match model. Only the combinatorial result of the components is a little different, since we do not count the mismatches in a component. This difference does not change the proof much. When $k$, the number of mismatches, is fixed, the terms related to $k$ can always be absorbed as a constant factor in the approximation. The following is the combinatorial lemma.
Lemma 4.2. Let $Y_{i}^{v}$ and $Y_{j}^{\mu}$ be the two dependent variables defined in this section and suppose that $i_{\nu}-i_{\mu} \neq j_{\nu}-j_{\mu}$. All the fragments in the two matching regions are separated into connected components. Let $x_{r}, r=2, \ldots, 2 t+1$, denote the number of $r$-components. Then

$$
\sum_{r=2}^{2 t+1} x_{r}(2(r-1))=4 t-4 k
$$

Figure 11 shows an example of the resulting components from two imperfect matching regions.

One difference from the exact match model in the imperfect match model is the selection of $t$, the asymptotic centring constant, to keep the $\lambda_{t, k}$ away from 0 and $\infty$. In analogy with the discussion of Arratia et al. (1986), we let

$$
t=\log _{1 / p}(n m)+k \log _{1 / p} \log _{1 / p}(n m)+s, \quad s>0
$$

Thus, $p^{t}=(n m)^{-1}\left(\log _{1 / p}(n m)\right)^{-k} p^{s}$. Therefore,

$$
\begin{aligned}
\lambda_{t, k} & \approx(a-p)(n-2 t+2)(m-2 t+2)\binom{t}{k}(1-p)^{k} p^{t-k} \\
& \approx \infty m p^{t} t^{k}(1-p)^{k} p^{-k} \\
& =(n m)(n m)^{-1} \frac{t^{k}}{\left(\log _{1 / p}(n)\right)^{k}} p^{s-k}(1-p)^{k} \\
& =\frac{t^{k}}{\left(\log _{1 / p}(n m)\right)^{k}} p^{s-k}(1-p)^{k}
\end{aligned}
$$

is bounded away from 0 and $\infty$, since $t / \log _{1 / p}(n m) \rightarrow 1$ as $n, m \rightarrow \infty$. Now, we can derive a corollary from Theorem 4.2 as we did in the exact match model.
Corollary 4.1. Under the same conditions on the relative growth rate of $n, m$ in the exact match model and letting $t=\log _{1 / p}(n m)+k \log _{1 / p} \log _{1 / p}(n m)+s$, $s>0$, there exist $C$, $\gamma>0$ such that

$$
\left|\mathrm{P}(W(t, k)=0)-\mathrm{e}^{-\lambda_{t, k}}\right| \leq C(\log n m)^{-\gamma} .
$$

### 4.2. Approximate distribution of $S_{n, m}^{k}$

In the previous section, we studied the approximate distribution of observing a window of size $t$ including $k$ mismatches. Fixing the number of mismatches, $k$, allowed in a window, the distribution of $S_{n, m}^{k}$ is studied in this section. We wish the approximate distribution of $W(t, k)$ to derive the tail probability of $S_{n, m}^{k}$ and have the following theorem.

Theorem 4.3. Let $S_{n, m}^{k}$ denote the length of maximum matching regions between $\boldsymbol{A}$ and $\boldsymbol{B}$ of length $n, m$ with at most $k$ mismatches. Under the conditions on the relative growth rate of $n$, $m, k$ and $t$ described in the last section, there exist $C_{1}, \gamma_{1}>0$ such that

$$
\left|\mathrm{P}\left(S_{n, m}^{k}<t\right)-\mathrm{e}^{-\lambda_{t, k}}\right|<C_{1}(\log n m)^{-\gamma_{1}}
$$

This result does not follow exactly as in the exact matching case. To derive this result from the previous results about $W(t, k)$, we fix the window size $t$ and find the distribution of the maximum number of matching pairs in all the windows of size $t$. Let $M_{t}$ denote the maximum number of matching pairs in a window of size $t$. It is obvious that $\left\{M_{t}<t-k\right\} \subset\{W(t, k)=0\}$. The inequality is due to the existence of windows with more than $t-k$ matching pairs.

Lemma 4.3. If there exists $v \in I$ such that $Y_{v}=1$, then there exists $v^{\prime} \in I$ such that $X_{v^{\prime}}=1$, which implies that $W(t, k)>0$.

The lemma states that the existence of a matching region of type $(t ; k)$ implies the existence of such a clump. Before we start the proof, for $v=\left(i_{\nu}, j_{\nu}\right), \mu=\left(i_{\mu}, j_{\mu}\right) \in I$, we define a partial order relation, $v<\mu$ if $i_{\mu}-i_{\nu}=j_{\mu}-j_{\nu}>0$.

Proof. If $Y_{v}=1$ for $v \in I$, then $X_{v}=1$ or there exists $v>\nu_{1} \in I$ such that $Y_{\nu_{1}}=1$ from the definition of $X_{v}$. If $X_{v}=1$, then we are done; otherwise, $Y_{\nu_{1}}=1$ implies that $X_{\nu_{1}}=1$ or $Y_{\nu_{2}}=1$ for some $\nu_{1}>\nu_{2} \in I$. Repeating this discussion, we obtain a strictly decreasing index series $v, v_{1}, \nu_{2}, \cdots \in I$ such that $Y_{\nu_{i}}=1$. Since the index set has lower bound $(1,1)$, the strictly decreasing index series stops at some $\nu_{h} \in I$, such that $Y_{v_{h}-l} \neq 1$ for $1 \leq l \leq t-1$, which implies that $X_{v_{h}}=1$.

The next theorem shows the difference of the probability between observing no window of size $t$ with $k$ mismatches and observing no window of size $t$ with $k$ mismatches but observing a window of size $t$ with less than $k$ mismatches.

Theorem 4.4. Let $M_{t}$ and $W(t, k)$ be defined as above, then

$$
0 \leq \mathrm{P}(W(t, k)=0)-\mathrm{P}\left(M_{t}<t-k\right) \leq C_{2}(\log n m)^{-\gamma_{2}},
$$

where $C_{2}, \gamma_{2}>0$ are two constants.
Proof. The first inequality is obvious since $\left\{M_{t}<t-k\right\} \subset\{W(t, k)=0\}$. When $M_{t} \geq t-k$, there exists at least one window with no more than $k$ mismatches. If this window has exactly $k$ mismatches, from Lemma 4.3 we know that $W(t, k)>0$. To have $W(t, k)=0$ and $M_{t} \geq t-k$, each window should have more or less than $k$ mismatches and at least one window with less than $k$ mismatches, say the window at $v=(i, j)$. Let $N_{t}(v)$ be the number of matching pairs in a window of size $t$ starting at $v$, which is then greater than $t-k$. The window starting at $v-1$ has at most one less matching pair than the window starting at $v$, so $N_{t}(v-1) \geq t-k$. In the case of equality, we can derive $W(t, k)>0$ from Lemma 4.3, hence strict inequality holds. We keep moving the window left by one pair until we reach the smallest possible index, and obtain

$$
\begin{cases}N_{t}((1,1))>t-k, & \text { if } i=j, \\ N_{t}((i-j+1,1))>t-k, & \text { if } i>j, \\ N_{t}((1, j-i+1))>t-k, & \text { if } i<j\end{cases}
$$

So, if $W(t, k)=0$ and $M_{t} \geq t-k$, at least one of the windows with at least one 1 in the starting point, as shown above, has more than $t-k$ matching pairs. Thus,

$$
\begin{aligned}
\mathrm{P}\left(W(t, k)=0 \text { and } M_{t} \geq t-k\right) & \leq(1+n-t+m-t) \mathrm{P}\left(N_{t}((1,1))>t-k\right) \\
& \leq 2(n \vee m) \sum_{l=0}^{k-1} p_{t, l} \leq 2 C(k)(n \vee m) t^{k} p^{t},
\end{aligned}
$$

since

$$
\sum_{l=0}^{k-1} p_{t, l}=\sum_{l=0}^{k-1}\binom{t}{l} p^{t-l}(1-p)^{l} \leq \sum_{l=0}^{k-1} t^{k} p^{t}\left(\frac{1-p}{p}\right)^{l} \leq C(k) t^{k} p^{t}
$$

where $C(k)$ is a constant depending on $k$ and $p$. Under the relative growth rate of $n, m$ and $\lambda_{t, k}, \lambda_{t, k} \approx_{\infty} n m t^{k} p^{t}$ is bounded away from 0 and $\infty$ as in Section 3.2,

$$
C(k)(n \vee m) t^{k} p^{t} \approx_{\infty} \begin{cases}(n m)^{\rho}(n m)^{-1}=(n m)^{\rho-1}, & \rho \geq \frac{1}{2}, \\ (n m)^{1-\rho}(n m)^{-1}=(n m)^{-\rho}, & \rho<\frac{1}{2},\end{cases}
$$

with $0<p<1$, which goes to zero when $n, m \rightarrow \infty$. So there exist $C_{2}, \gamma_{2}>0$ such that

$$
\mathrm{P}(W(t, k)=0)-\mathrm{P}\left(M_{t}<t-k\right) \leq C_{2}(\log n m)^{-\gamma_{2}}
$$

Combined with Theorem 4.1, the tail probability of $M_{t}$ can be approximated by the following theorem.

Theorem 4.5. Under the same conditions on the growth rate of $n, m$ and $t$ as in Corollary 4.1, there exist $C_{1}, \gamma_{1}>0$ such that

$$
\left|\mathrm{P}\left(M_{t}<t-k\right)-\mathrm{e}^{-\lambda_{t, k}}\right| \leq C_{1}(\log n m)^{-\gamma_{1}}
$$

under certain conditions for the relative growth rate of $n, m$ and $t$ as described in Theorem 4.3.
This can be proved easily, since

$$
\begin{aligned}
\left|\mathrm{P}\left(M_{t}<t-k\right)-\mathrm{e}^{-\lambda_{t, k}}\right| & \leq\left|\mathrm{P}\left(M_{t}<t-k\right)-\mathrm{P}(W(t, k)=0)\right|+\left|\mathrm{P}(W(t, k)=0)-\mathrm{e}^{-\lambda_{t, k}}\right| \\
& \leq C(\log n m)^{-\gamma}+C_{2}(\log n m)^{-\gamma_{2}} \\
& \leq C_{1}(\log n m)^{-\gamma_{1}},
\end{aligned}
$$

for some $C_{1}, \gamma_{1}>0$.
Now we return to the distribution of $S_{n, m}^{k}$. For any $t$, we have the following equivalences: $S_{n, m}^{k}<t \quad \Longleftrightarrow \quad$ there is no window of size no smaller than $t$ with $k$ or fewer mismatches
$\Longleftrightarrow \quad$ there is no window of size $t$ with $k$ or fewer mismatches

$$
\Longleftrightarrow \quad M_{t}<t-k
$$

Therefore,

$$
\mathrm{P}\left(S_{n, m}^{k}<t\right)=\mathrm{P}\left(M_{t}<t-k\right)
$$

and Theorem 4.3 is proved through Theorem 4.5.

## 5. Open problem

Since mutations occur in DNA sequences, it is possible that a mutation might create a new cut site or make an existing cut site disappear. When a cut site is mutated into a non-cut-site, the two fragments from the cut site in the restriction map of the DNA sequence before the mutation merge into one big fragment in the restriction map of the DNA sequence after the mutation. A mutation causing a new cut site divides one fragment including the new cut site into two smaller fragments. To make our results more powerful and useful, we consider this kind of mutation in restriction map matching. This matching is considered in a general form in the algorithms of Huang and Waterman (1992).

The mutation of a cut site might result in the merge of two restriction fragments to one fragment or vice versa, so we allow a few merge-matches in a matching region as depicted in Figure 12. A merge-match is defined to occur when the sum of lengths of two adjacent


Figure i2: An example of a matching region of length 5 including 2 merge-matches, $A_{3}=\nabla B_{3}+B_{4}$ and $A_{6}+A_{7}={ }_{\nabla} B_{7}$.
fragments differs from the length of the corresponding fragment by no more than $\sigma$. Three fragments are involved in a merge-match. A mutation in a cut site might induce a merge-match.

For fixed $t$ and $k$, a matching region of length $t$ is defined as a long run of $t$ matching fragment pairs except for at most $k$ merge-matches between two restriction maps. The authors undertook a study of this type of matching regions, wishing to obtain similar results to those obtained for exact matchings and imperfect matchings. Because the merge-match brings greater complexity to the combinatorial analysis in the study, no good results have yet been obtained. The statistical results for this more complicated matching will be more powerful in detecting significant similarity between maps.

For practical application, we recommend simulation studies as in Waterman and Vingron (1994). At the basis of that work was a decomposition of the scoring parameter space into linear and logarithmic growth. The corresponding generalization of Arratia and Waterman (1989) could be established for map matching.

## Appendix A. Proof of Lemma 3.2

To show the relation between $p$ and $p_{3}$, we compute them from the exponential distribution first:

$$
\begin{aligned}
p & =\mathrm{P}\left(A_{1}=\nabla A_{2}\right)=\mathrm{P}\left(\left|A_{1}-A_{2}\right|<\sigma\right) \\
& =\int_{0}^{\sigma} \int_{0}^{x+\sigma} \lambda \mathrm{e}^{-\lambda x} \lambda \mathrm{e}^{-\lambda y} \mathrm{~d} y \mathrm{~d} x+\int_{\sigma}^{\infty} \int_{x-\sigma}^{x+\sigma} \lambda \mathrm{e}^{-\lambda x} \lambda \mathrm{e}^{-\lambda y} \mathrm{~d} y \mathrm{~d} x \\
& =\int_{0}^{\sigma} \lambda \mathrm{e}^{-\lambda x}\left(1-\mathrm{e}^{-\lambda(\sigma+x)}\right) \mathrm{d} x+\int_{\sigma}^{\infty} \lambda \mathrm{e}^{-\lambda x}\left(\mathrm{e}^{-\lambda(x-\sigma)}-\mathrm{e}^{-\lambda(x+\sigma)}\right) \mathrm{d} x \\
& =\left(1-\mathrm{e}^{-\lambda \sigma}\right)+\frac{1}{2} \mathrm{e}^{-\lambda \sigma}\left(\mathrm{e}^{-2 \lambda \sigma}-1\right)+\frac{1}{2}\left(\mathrm{e}^{\lambda \sigma}-\mathrm{e}^{-\lambda \sigma}\right) \mathrm{e}^{-2 \lambda \sigma} \\
& =1-\mathrm{e}^{-\lambda \sigma},
\end{aligned}
$$

and

$$
\begin{aligned}
p_{3}= & \mathrm{P}\left(A_{1}={ }_{\nabla} A_{2} \text { and } A_{2}={ }_{\nabla} A_{3}\right) \\
= & \mathrm{P}\left(\left|A_{1}-A_{2}\right|<\sigma \text { and }\left|A_{2}-A_{3}\right|<\sigma\right) \\
= & \int_{0}^{\sigma} \int_{0}^{x+\sigma} \int_{0}^{x+\sigma} \lambda \mathrm{e}^{-\lambda x} \lambda \mathrm{e}^{-\lambda y} \lambda \mathrm{e}^{-\lambda z} \mathrm{~d} z \mathrm{~d} y \mathrm{~d} x \\
& +\int_{\sigma}^{\infty} \int_{x-\sigma}^{x+\sigma} \int_{x-\sigma}^{x+\sigma} \lambda \mathrm{e}^{-\lambda x} \lambda \mathrm{e}^{-\lambda y} \lambda \mathrm{e}^{-\lambda z} \mathrm{~d} z \mathrm{~d} y \mathrm{~d} x \\
= & \int_{0}^{\sigma} \lambda^{-\lambda x}\left(1-\mathrm{e}^{-\lambda(x+\sigma)}\right)^{2} \mathrm{~d} x+\int_{\sigma}^{\infty} \lambda \mathrm{e}^{-\lambda x}\left(\mathrm{e}^{-\lambda(x-\sigma)}-\mathrm{e}^{-\lambda(x+\sigma)}\right)^{2} \mathrm{~d} x \\
= & \mathrm{e}^{\lambda \sigma} \int_{0}^{\sigma}\left(1-\mathrm{e}^{-\lambda \sigma-\lambda x}\right)^{2} \mathrm{~d}\left(1-\mathrm{e}^{-\lambda \sigma-\lambda x}\right) \\
& +\left(\mathrm{e}^{\lambda \sigma}-\mathrm{e}^{-\lambda \sigma}\right)^{2} \int_{\sigma}^{\infty} \lambda \mathrm{e}^{-\lambda x} \mathrm{e}^{-2 \lambda x} \mathrm{~d} x \\
= & \frac{1}{3} \mathrm{e}^{\lambda \sigma}\left(\left(1-\mathrm{e}^{-2 \lambda \sigma}\right)^{3}-\left(1-\mathrm{e}^{-\lambda \sigma}\right)^{3}\right)+\frac{1}{3}\left(\mathrm{e}^{\lambda \sigma}-\mathrm{e}^{-\lambda \sigma}\right)^{2} \mathrm{e}^{-3 \lambda \sigma} \\
= & \frac{1}{3} \mathrm{e}^{\lambda \sigma}\left(\left(1-\mathrm{e}^{-2 \lambda \sigma}\right)^{3}-\left(1-\mathrm{e}^{-\lambda \sigma}\right)^{3}\right)+\frac{1}{3} \mathrm{e}^{-\lambda \sigma}\left(1-\mathrm{e}^{-2 \lambda \sigma}\right)^{2} .
\end{aligned}
$$

Next, $p_{3}$ is written in terms of $p$. Since $p=1-\mathrm{e}^{-\lambda \sigma}, \mathrm{e}^{-\lambda \sigma}=1-p$, and then

$$
\begin{aligned}
p_{3} & =\frac{1}{3(1-p)}\left(\left(1-(1-p)^{2}\right)^{3}-p^{3}\right)+\frac{1}{3}(1-p)\left(1-(1-p)^{2}\right)^{2} \\
& =\frac{\left(1-(1-p)^{2}\right)^{2}}{3}\left(\frac{1-(1-p)^{2}}{(1-p)}+(1-p)\right)-\frac{p^{3}}{3(1-p)} \\
& =\frac{\left(p^{2}-2 p\right)^{2}}{3} \frac{1}{(1-p)}-\frac{p^{3}}{3(1-p)} \\
& =\frac{p^{2}}{3(1-p)}\left((p-2)^{2}-p\right)=\frac{p^{2}}{3(1-p)}\left((p-1)^{2}+3(1-p)\right) \\
& =p^{2}\left(\frac{1}{3}(1-p)+1\right)=p^{3 / 2} \sqrt{p}\left(\frac{1}{3}(1-p)+1\right)=p^{3 / 2} h(p),
\end{aligned}
$$

where

$$
h(p)=\sqrt{p}\left(\frac{1}{3}(1-p)+1\right)=\sqrt{p}\left(\frac{4}{3}-\frac{1}{3} p\right)
$$

To show that $p_{3}<p^{3 / 2}$, we only need show that $h(p)<1$ for $0<p<1$. Consider the derivative of $h(p)$ :

$$
h^{\prime}(p)=\frac{4}{3} \frac{1}{2} p^{-1 / 2}-\frac{1}{3} \frac{3}{2} \sqrt{p}=\frac{2}{3 \sqrt{p}}\left(1-\frac{3}{4} p\right)>0, \quad \text { when } 0<p<1
$$

so $h(p)$ is increasing in $(0,1)$, and $h(p)<h(1)=1$ when $0<p<1$. Therefore, $p_{3}<p^{3 / 2}$ and there exists a constant $c>0$ such that $p_{3}=p^{3 / 2+3 c}$. From the above, we have

$$
p_{3}=p^{2}\left(\frac{1}{3}(1-p)+1\right)>p^{2}
$$

which implies that

$$
\frac{3}{2}+3 c<2, \quad \text { that is } \quad c<\frac{1}{6}
$$

Now, we can conclude that

$$
p_{3}=p^{3 / 2+3 c}, \quad \text { where } 0<c<\frac{1}{6}
$$

## Appendix B. Proof of Lemma 3.3

It is obvious that the event $\left\{A_{1}={ }_{\nabla} A_{2}\right.$ and $A_{2}={ }_{\nabla} A_{3}$ and $\left.\ldots A_{r-1}={ }_{\nabla} A_{r}\right\}$ is included in the event $\left\{A_{1}={ }_{\nabla} A_{2}\right.$ and $A_{2}={ }_{\nabla} A_{3}, A_{4}={ }_{\nabla} A_{5}$ and $\left.A_{5}={ }_{\nabla} A_{6}, \ldots\right\}$. To show the inequality for $p_{r}$, the upper bound for the latter is found,

$$
\begin{aligned}
p_{r} & =\mathrm{P}\left(A_{1}={ }_{\nabla} A_{2} \text { and } A_{2}={ }_{\nabla} A_{3} \text { and } \ldots A_{r-1}={ }_{\nabla} A_{r}\right) \\
& \leq \mathrm{P}\left(A_{1}={ }_{\nabla} A_{2} \text { and } A_{2}={ }_{\nabla} A_{3}, A_{4}={ }_{\nabla} A_{5} \text { and } A_{5}={ }_{\nabla} A_{6}, \ldots\right) \\
& =\mathrm{P}\left(A_{1}={ }_{\nabla} A_{2} \text { and } A_{2}={ }_{\nabla} A_{3}\right) \mathrm{P}\left(A_{4}={ }_{\nabla} A_{5} \text { and } A_{5}={ }_{\nabla} A_{6}\right) \ldots .
\end{aligned}
$$

Above, the $r$ fragments are divided into small distinct groups with three fragments in each group, except that the last group might have fewer than three fragments. We will discuss three cases. Let $r=a, \bmod 3$, and $a=0,1$ or 2 . We discuss the three cases separately.

Case 1. For $a=0$,

$$
\begin{aligned}
p_{r} & \leq \mathrm{P}\left(A_{1}=\nabla A_{2} \text { and } A_{2}=\nabla A_{3}\right) \cdots \mathrm{P}\left(A_{r-2}=\nabla A_{r-1} \text { and } A_{r-1}=\nabla A_{r}\right) \\
& =p_{3}^{r / 3} \leq p_{3}^{r / 3} p^{-(1 / 2+c)} .
\end{aligned}
$$

Case 2. For $a=1$,

$$
\begin{aligned}
p_{r} & \leq \mathrm{P}\left(A_{1}=\nabla A_{2} \text { and } A_{2}=\nabla A_{3}\right) \cdots \mathrm{P}\left(A_{r-3}=\nabla A_{r-2} \text { and } A_{r-2}=\nabla A_{r-1}\right) \\
& =p_{3}^{k}=p_{3}^{r / 3} p_{3}^{-1 / 3}=p_{3}^{r / 3} p^{-(1 / 3)(3 / 2+3 c)}=p_{3}^{r / 3} p^{-(1 / 2+c)}
\end{aligned}
$$

Case 3. For $a=2$,

$$
\begin{aligned}
p_{r} \leq & \mathrm{P}\left(A_{1}={ }_{\nabla} A_{2} \text { and } A_{2}={ }_{\nabla} A_{3}\right) \cdots \mathrm{P}\left(A_{r-4}={ }_{\nabla} A_{r-3} \text { and } A_{r-3}={ }_{\nabla} A_{r-2}\right) \\
& \times \mathrm{P}\left(A_{r-1}={ }_{\nabla} A_{r}\right) \\
= & p_{3}^{k} p=p_{3}^{r / 3} p_{3}^{-2 / 3} p=p_{3}^{r / 3} p^{-(2 / 3)(3 / 2+3 c)} p=p_{3}^{r / 3} p^{-(1+2 c)+1} \\
= & p_{3}^{r / 3} p^{-2 c} \leq p_{3}^{r / 3} p^{-(1 / 2+c)},
\end{aligned}
$$

since $c<\frac{1}{6}$, then $2 c<\frac{1}{3}<\frac{1}{2}+c$.
Combining the above results, we obtain

$$
p_{r} \leq p_{3}^{r / 3} p^{-(1 / 2+c)}<\left(p^{3 / 2+3 c}\right)^{r / 3} p^{-(1 / 2+c)}=p^{(1 / 2+c)(r-1)} .
$$

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