

Fall 2010 #1

Compute $\pi_1(X_1), \pi_1(X_2)$ for $X_1 =$  and $X_2 =$ 

These are CW complexes. Let $A =$  which is contractible, and since (X_1, A) good pair we get

$$\pi_1(X_1) \approx \pi_1(X_1/A) = \pi_1(S^1 \vee S^1 \vee S^1) = \boxed{\mathbb{Z} * \mathbb{Z} * \mathbb{Z}}$$

$B =$  is contractible as well and (X_2, B) good pair.

Then collapsing it gives  $= S^1 \vee S^1 \vee S^1 \vee S^1$

$$\text{Thus } \pi_1(X_2) \approx \pi_1(X_2/B) = \pi_1(S^1 \vee S^1 \vee S^1 \vee S^1) = \boxed{\mathbb{Z} * \mathbb{Z} * \mathbb{Z} * \mathbb{Z}}$$

Fall 2010 #2

Let p_1, p_2, p_3 be three distinct points in S^2

$X = S^2 / \{p_1, p_2, p_3\}$. Compute $H_n(X; \mathbb{Z})$.

$S^2 / \{p_1, p_2, p_3\}$ is homotopy equivalent to S^2 union two 1-cells glued from p_1 to p_2 and from p_2 to p_3 . This is because these two 1-cells are contractible and form a good pair with S^2 . Then this is homotopy equivalent with $S^2 \vee S^1 \vee S^1$ by collapsing the paths in S^2 connecting p_1 to p_2 and p_2 to p_3 .

$$\begin{aligned} \text{Hence } \tilde{H}_n(X) &\approx \tilde{H}_n(S^2 \vee S^1 \vee S^1) = \tilde{H}_n(S^2) \oplus \tilde{H}_n(S^1) \oplus \tilde{H}_n(S^1) \\ &= \begin{cases} \mathbb{Z} & n=2 \\ \mathbb{Z} \oplus \mathbb{Z} & n=1 \\ 0 & \text{else} \end{cases} \end{aligned}$$

Thus

$$H_n(X) = \begin{cases} \mathbb{Z} & n=0, 2 \\ \mathbb{Z} \oplus \mathbb{Z} & n=1 \\ 0 & \text{else} \end{cases}$$

Fall 2010 #3

Gauss Bonnet

Fall 2010 #4

(Daniel)

$$M_n(\mathbb{R}) = \{n \times n \text{ matrices}\}. \quad O(n) = \{A \in M_n(\mathbb{R}) : AA^T = I\}$$

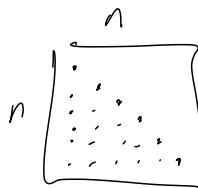
Claim: $O(n)$ smooth mfd. what is its dimension?

$$\text{Define } f: M_n(\mathbb{R}) \rightarrow \text{Sym}_n(\mathbb{R})$$

$$A \mapsto AA^T$$

$$df_A: T_A M_n(\mathbb{R}) \rightarrow T_{AA^T} \text{Sym}_n(\mathbb{R})$$

$$\mathbb{R}^{n^2} \rightarrow \mathbb{R}^{n(n+1)/2}$$



$$n + n-1 + n-2 + n-3 + \dots + 1 + 1 + 1$$

$$= n^2 - \sum_{i=1}^{n-1} i$$

$$= n^2 - \frac{n(n-1)}{2}$$

$$= \frac{2n^2 - n^2 + n}{2} = \frac{n^2 + n}{2}$$

$$= \frac{n(n+1)}{2}$$

$$df_A(B) = \left. \frac{d}{dt} \right|_{t=0} f(A + tB)$$

$$= \lim_{h \rightarrow 0} \frac{f(A+hB) - f(A)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{(A+hB)(A+hB)^T - AA^T}{h}$$

$$= \lim_{h \rightarrow 0} \frac{\cancel{AA^T} + AhB^T + hBA^T + hBhB^T - \cancel{AA^T}}{h}$$

$$= AB^T + BA^T + \cancel{hBB^T}$$

So for $C \in \text{Sym}_n(\mathbb{R})$ if $\exists B$ s.t. $C = AB^T + BA^T$
 then df_A surjective and ± 1 reg. value $\Rightarrow O(n)$ submfd.

Indeed, let $B = \frac{1}{2}CA$. Then $AB^T + BA^T = \frac{1}{2}AA^TC + \frac{1}{2}CAA^T = C$

since $f(A) = I$. Dimension is then $n^2 - n(n+1)/2 = n(n-1)/2$.

Fall 2010 #5

$$\omega \in \Omega^{n-1}(\mathbb{R}^n - \{0\}) \quad d\omega = dx_1 \wedge \dots \wedge dx_n$$

$$\text{Claim: } \forall p \in \mathbb{R}, \quad \alpha = \frac{1}{(x_1^2 + \dots + x_n^2)^p} \omega \in \Omega^{n-1}(\mathbb{R}^n - \{0\})$$

is not exact. Hint: S^{n-1}

If α exact, then $\exists \eta \in \Omega^{n-2}(\mathbb{R}^n - \{0\})$ s.t. $\alpha = d\eta$.

$$\text{Then by Stokes, } \int_{S^{n-1}} \alpha = \int_{S^{n-1}} d\eta = \int_{\partial S^{n-1}} \eta = 0$$

But $\alpha = \omega$ on S^{n-1} $\forall p \in \mathbb{R}$, so by Stokes again

$$\int_{S^{n-1}} \alpha = \int_{S^{n-1}} \omega = \int_{B^n - \{0\}} d\omega = \text{Vol}(B^n - \{0\}) \neq 0.$$

Fall 2010 #6

$\omega = \sum_{i=1}^n dx_i \wedge dy_i$ on $\mathbb{R}^{2n}$ w/ words $x_1, y_1, \dots, x_n, y_n$.

$f: \mathbb{R}^{2n} \rightarrow \mathbb{R}$ smooth, Find vect. field X s.t.

$i_X \omega = df$ where i_X denotes the interior product. Then

compute Lie derivative $\mathcal{L}_X \omega$.

Recall: $(i_X \omega)_p(v) = \omega_p(X_p, v)$ for $p \in \mathbb{R}^{2n}$, $v \in T_p \mathbb{R}^{2n}$

$$dx_i \wedge dy_i(X_p, v) = \det \begin{pmatrix} x_i(X_p) & x_i(v) \\ y_i(X_p) & y_i(v) \end{pmatrix} = x_i(X_p) y_i(v) - x_i(v) y_i(X_p)$$

$$\omega_p(X_p, v) = \sum_{i=1}^n x_i(X_p) y_i(v) - x_i(v) y_i(X_p)$$

$$df_p(v) = \sum_{i=1}^n \left. \frac{\partial f}{\partial x_i} \right|_p x_i(v) + \left. \frac{\partial f}{\partial y_i} \right|_p y_i(v)$$

$$\text{Hence } x_i(X) = \frac{\partial f}{\partial y_i} \text{ and } y_i(X) = \frac{\partial f}{\partial x_i}$$

By Cartan's magic formula,

$$\mathcal{L}_X \omega = X \lrcorner d\omega + d(X \lrcorner \omega) = X \lrcorner d\omega + \cancel{d(df)} = X \lrcorner d\omega$$

$$d\omega = 0 \text{ so } X \lrcorner 0 = 0 \Rightarrow \mathcal{L}_X \omega = 0.$$

Fall 2010 # 7

X top. space. $H_p(X; \mathbb{Z})$ finite. $H^{p+1}(X; \mathbb{Q}) = 0$.

$u \in C^{p+1}(X; \mathbb{Z}) = \text{Hom}(C_{p+1}(X; \mathbb{Z}), \mathbb{Z})$, $\partial u = 0$.

(a) Show $\forall \alpha \in C_p(X; \mathbb{Z})$ with $\partial \alpha = 0$, $\exists k \in \mathbb{Z} - \{0\}$ and $\beta \in C_{p+1}(X; \mathbb{Z})$ with $k\alpha = \partial \beta$.

$[\alpha] \in H_p(X; \mathbb{Z})$, a finite group $\Rightarrow k[\alpha] = 0 \in H_p(X; \mathbb{Z})$
for some $k \in \mathbb{Z} - \{0\}$. That means $[k\alpha] = 0$
 $\Rightarrow k\alpha = \partial \beta$ for some $\beta \in C_{p+1}(X; \mathbb{Z})$. $\square$

(b) Show $\exists$ hom $L_u: H_p(X; \mathbb{Z}) \rightarrow \mathbb{Q}/\mathbb{Z}$
s.t. $L_u([\alpha]) = \frac{1}{k} u(\beta)$ for every $k \in \mathbb{Z} - \{0\}$
and $\beta \in C_{p+1}(X; \mathbb{Z})$ with $k\alpha = \partial \beta$.

Namely show that $L_u([\alpha])$ independent of k, β and
or representative α of $[\alpha]$.

$\partial u = 0 \Rightarrow [u] \in H^{p+1}(X; \mathbb{Q}) = 0 \Rightarrow \exists v \in C^p(X; \mathbb{Z})$

s.t. $\partial v = u$. Thus for β' with $k\alpha = \partial \beta'$ as well, we have

$$u(\beta') = \partial v(\beta') = v(\partial \beta') = v(k\alpha) = v(\partial \beta) = \partial v(\beta) = u(\beta).$$

k and k' are the same by order.