FIRST NAME:

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SIGNATURE:

PROBLEM 1 Consider the following 3×3 matrix:

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & \epsilon & \epsilon \\ 0 & \epsilon & \epsilon + \epsilon^2 \end{pmatrix}$$

- (a) Use the Gram-Schmidt orthogonalization method on the columns of matrix A to derive a QR-decomposition of A.
- (b) Use the Householder QR-factorization method to perform the same task as (a).
- (c) Based on your calculations in (a) and (b), determine which method would lead to a more accurate factorization on an actual computer and justify your reasoning.
- (d) A graduate student programmed both techniques in Matlab and tested them for the case $\epsilon = 10^{-10}$. He evaluated the norm of A - Q * R in Matlab and found that the norm was equal to 0 for the Gran-Schmidt factorization and 4.6032×10^{-26} for the Householder factorization. Is this consistent with your conclusion in (c)? What other quantities would you suggest him to examine that may support your conclusion in (c)?

PROBLEM 2. Let A be an $n \times n$ real-valued, symmetric positive definite matrix and $b \in \mathbb{R}^n$. Consider the following two-stage iterative procedure for solving the system of equations Ax = b:

$$\begin{aligned} x_{n+\frac{1}{2}} &= x_n + \omega_1 (b - Ax_n) \\ x_{n+1} &= x_{n+\frac{1}{2}} + \omega_2 (b - Ax_{n+\frac{1}{2}}) \end{aligned}$$

- (a) Let $e_n = x x_n$ be the error between the *n*-th iterate x_n and the exact solution x. Find the matrix K such that $e_{n+1} = Ke_n$.
- (b) Find the eigenvalues of K in terms of the eigenvalues of A, ω_1 , and ω_2 .
- (c) Show that ω_1 and ω_2 can be chosen so that the method converges with any initial condition. Express the rate of convergence in terms of λ_M and λ_m which correspond to the largest and smallest eigenvalues of A, respectively.

PROBLEM 3. Consider a least square minimization problem:

minimize
$$||Ax - b||_2^2$$
, $x \in \mathbb{R}^n, b \in \mathbb{R}^m$, (1)

and a regularized form of the (1):

minimize
$$||Ax - b||_2^2 + \alpha ||x||_2^2$$
, $\alpha > 0.$ (2)

- (a) State and justify a necessary and sufficient condition for a vector x_0 to be a solution of (1) and determine whether or not this problem always has a unique solution?
- (b) State and justify a necessary and sufficient condition for a vector x_0 to be a solution of (2) and determine whether or not this problem always has a unique solution?
- (c) Let $\mathcal{R}(A^T)$ be the range of A^T and let $\mathcal{N}(A)$ be the null space of A. Explain why a solution of (2) must be in $\mathcal{R}(A^T)$.
- (d) Suggest a method for approximating a minimal norm solution of (1) using a sequence of solutions of (2) and justify your answer.

PROBLEM 4. Let A be an $n \times n$ skew-Hermitian (i.e. $A^H = -A$) matrix.

- (a) Show that I + A is invertible.
- (b) Show that $U = (I + A)^{-1}(I A)$ is unitary.
- (c) Show that if U is unitary with $-1 \notin \sigma(U)$, then there exists a skew-Hermetian matrix A such that $U = (I + A)^{-1}(I - A)$.
- (d) Show that if B is an $n \times n$ normal matrix (i.e. $B^H B = BB^H$) then it is unitarily similar to a diagonal matrix.
- (e) Let C be an $n \times n$ matrix with singular values $\sigma_1 \ge \sigma_2 \ge \cdots \ge \sigma_n \ge 0$. Show that if λ is an eigenvalue of C, then $|\lambda| \le \sigma_1$ and that $|\det(C)| = \prod_{i=1}^n \sigma_i$.